

# A rák megszelítítése irányításelméleti módszerekkel

## Taming cancer using control engineering methods

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- Main concept
- Discrete therapy as an optimization problem
- Continuous therapy

## 2 Tumor model and analysis

- Model equations
- The closed-loop system
- The equilibria of the closed-loop system



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# Main concept of the research



**Medical knowledge**



cancer treatments

general protocols



**Healing of the patient**

find more effective solutions in healing  
individual treatment for the patient

model identification

model-based protocols



**Engineering knowledge**





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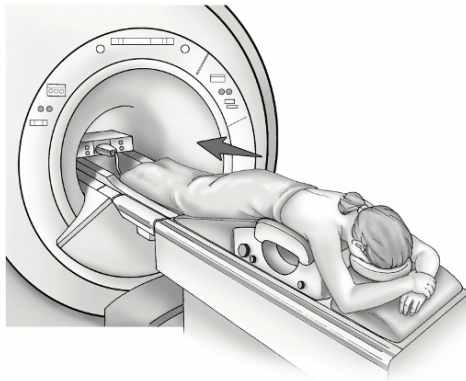
# The treatment scenario

The patient **visits** the doctor in **fixed intervals**. We will call this interval the sampling time, denote it by  $T_s$  and measure it in **days**.



# The treatment scenario

At each visit, the doctor **examines** the patient, and we suppose that as a result **all** internal **states** (tumor volume, endothelial volume, inhibitor serum level) **become available**.



© Stan and Amy Collins

Breast MRI



# The treatment scenario

The doctor defines the **desired tumor volume** for the next investigation. The **minimal** amount of **drug** injection that is required to reach the desired tumor volume **is calculated** using the tumor growth model and the information acquired from the measurements in the previous step using an optimization **algorithm**.





# The optimization problem

- At the  $k$ th investigation ( $k$ th step) we know the internal states of the system  $x_1[k] := x_1(kT_s)$ ,  $x_2[k] := x_2(kT_s)$ , and  $g[k] := g(kT_s)$ .
- The desired tumor volume for the next step is denoted by  $x_{1,d}[k + 1]$ .
- We are looking for the minimal amount of injection  $u[k]$  such that the tumor volume in the next step is less than or equal to the desired tumor volume, i.e.  $x_1[k + 1] \leq x_{1,d}[k + 1]$ .



# The optimization algorithm

**Input:** The initial values  $x_1[k]$ ,  $x_2[k]$  and  $g[k]$ . The *TOL* accuracy of the solution. The desired tumor volume  $x_{1,d}[k+1]$ . The maximal drug injection *UMAX*.

**Result:** The minimal drug dosage  $u[k]$  that is required to reach the desired tumor volume in the next step.



# The optimization algorithm

```
Let  $u_{\max} = UMAX$  and  $u_{\min} = 0$   
while  $u_{\max} - u_{\min} > TOL$  do  
   $u = (u_{\max} - u_{\min})/2$  Calculate the tumor volume in the next  
  time instant  $(k + 1)T_s$  by solving the initial value problem on  
  time interval  $[kT_s, (k + 1)T_s]$  defined by the model with initial  
  values  $x_1[k], x_2[k], g[k] + u$ ; denote it by  $x_1[k + 1]$   
  if  $x_1[k + 1] > x_{1,d}[k + 1]$  then  
     $u_{\min} := u$   
  else  
     $u_{\max} := u$   
  end  
end
```



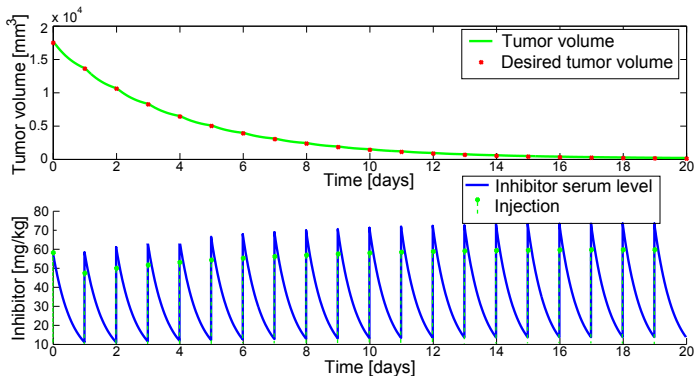
# Optimal solution

The previous algorithm is a **binary search algorithm**, thus it only works if the model output is **monotonous** in the input.

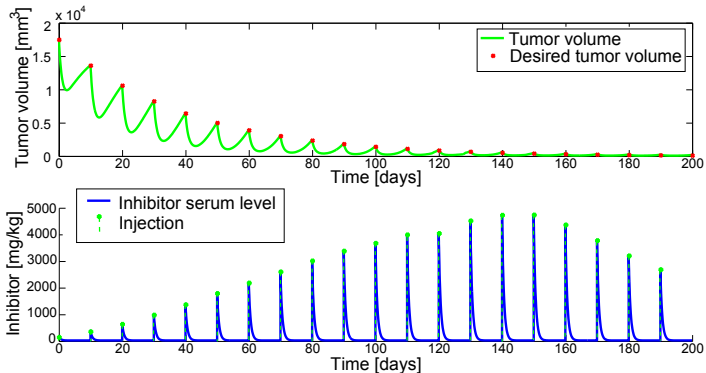
## Theorem

*The output of the Hahnfeldt-model with linear pharmacokinetics is monotonous in the input.*

$$T_s = 1 \text{ day}, x_{1,d}[k] = x_1(0) \exp(-4k)$$

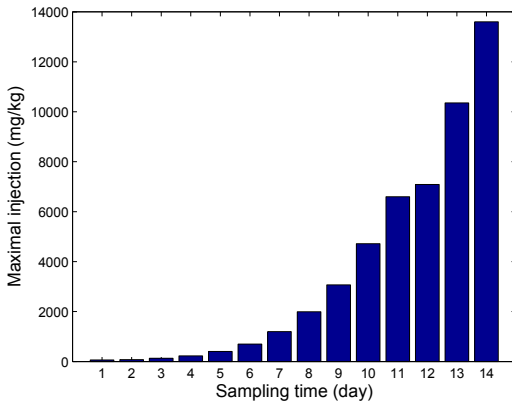


$$T_s = 10 \text{ day}, x_{1,d}[k] = x_1(0) \exp(-4k)$$





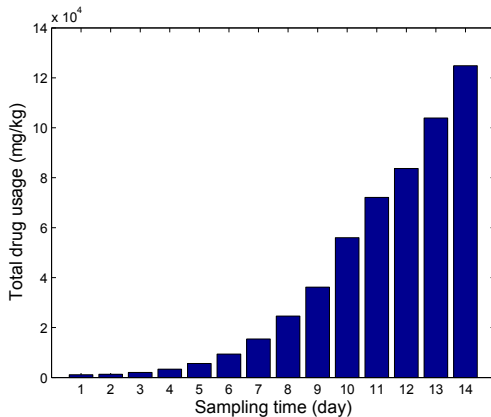
# Maximal injection vs. Sampling Time





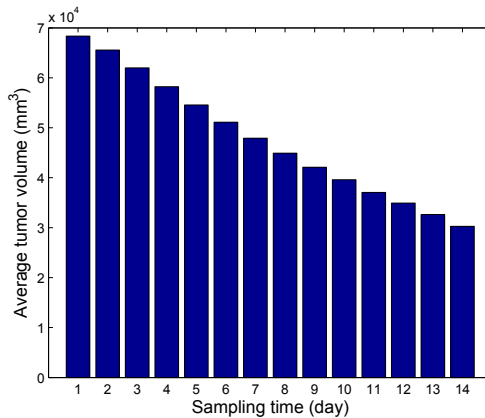


# Total inhibitor vs. Sampling Time





# Average tumor volume vs. Sampling Time





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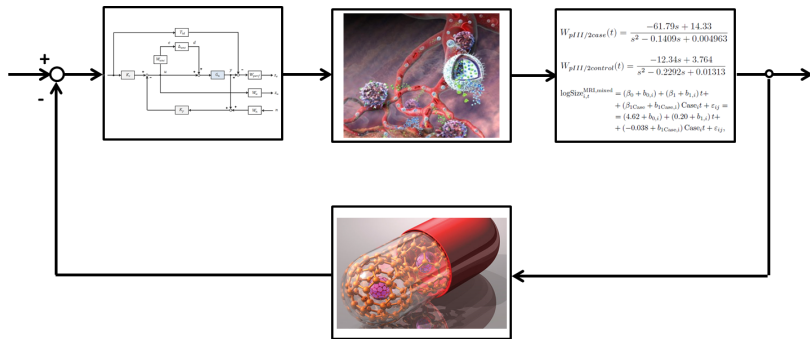
## 2 Tumor model and analysis

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# Artificial pancreas



# Future concept





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# Modeling the effect of bevacizumab

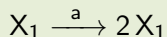
$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$

- $x_1$  volume of the proliferating tumor cells [ $\text{mm}^3$ ];
- $x_2$  volume of the necrotic tumor cells [ $\text{mm}^3$ ];
- $x_3$  serum level of the drug [ $\text{mg/ml}$ ];
- $y = x_1 + x_2$  measured tumor volume [ $\text{mm}^3$ ];
- $u$  drug injection rate [ $\text{mg/ml/day}$ ].



# Modeling the effect of bevacizumab: tumor proliferation

Tumor proliferation (mass-action kinetics)

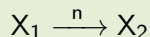


$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$



# Modeling the effect of bevacizumab: tumor necrosis

Tumor necrosis (mass-action kinetics)

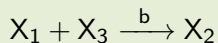


$$\begin{aligned} \dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u, \end{aligned}$$



# Modeling the effect of bevacizumab: effect of the drug

## Effect of the drug (Michaelis-Menten kinetics), pharmacodynamics

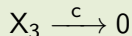


$$\begin{aligned} \dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u, \end{aligned}$$



# Modeling the effect of bevacizumab: depletion of the drug

Depletion of the drug (Michaelis-Menten kinetics), mixed-order pharmacokinetics



$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$



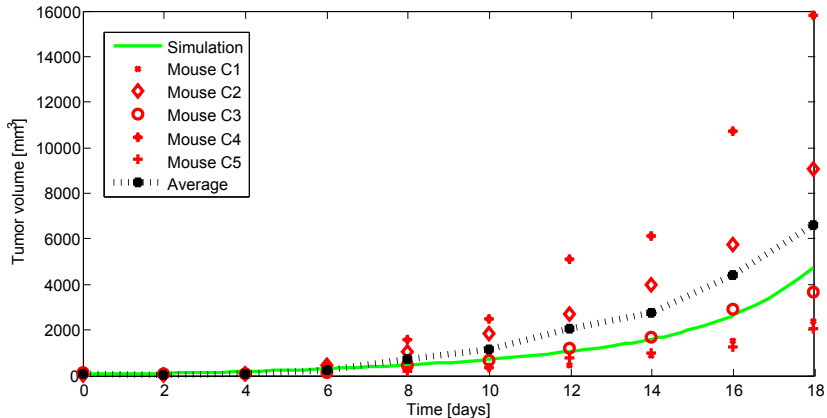
# Modeling the effect of bevacizumab: the input

The input of the model increases the drug serum level

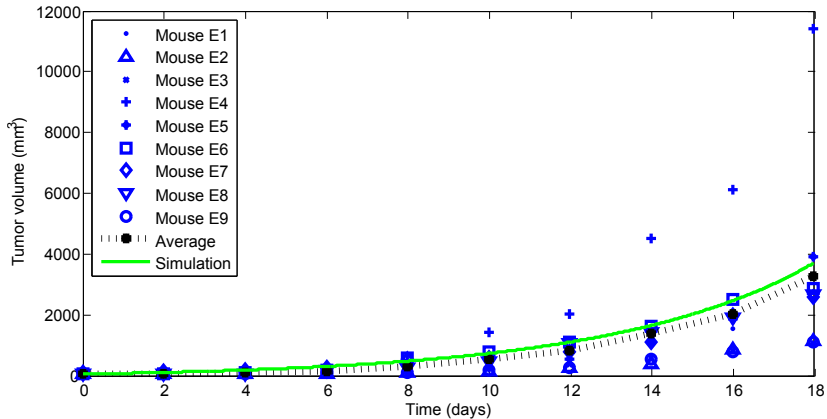
$$u \geq 0$$

$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$

# Model validation and measurements (one injection)



# Model validation and measurements (daily injections)





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# Model equations

## Model reduction

$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_2 &= nx_1 + b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$

The second equation can be omitted since the other equations do not depend on  $x_2$ .

# Model equations, closed-loop system

## Planar system

$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + u,\end{aligned}$$

## Closed-loop system

The applied control law is state feedback, i.e.  $u = k_1 x_1 - k_3 x_3$ .  
Thus, the model of the closed-loop system is

$$\begin{aligned}\dot{x}_1 &= ax_1 - nx_1 - b \frac{x_1 x_3}{ED_{50} + x_3} \\ \dot{x}_3 &= -c \frac{x_3}{K_B + x_3} - b_{\kappa} \frac{x_1 x_3}{ED_{50} + x_3} + k_1 x_1 - k_3 x_3.\end{aligned}$$



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# Equilibria of the closed-loop system

## First equilibrium

$$x_1^* = 0, x_3^* = 0.$$

The eigenvalues of the linearized system are

$$\lambda_1 = -ED_{50} \frac{c + k_3 K_B}{K_B} < 0$$

$$\lambda_2 = ED_{50}(a - n).$$

If  $a - n > 0$ , then the tumor grows (the growth rate is larger than the necrotic rate), in this case this point is a saddle (the tumor grows, the drug depletes).

If  $a - n < 0$ , then the tumor shrinks (the growth rate is smaller than the necrotic rate), in this case this point is a stable node.



# Equilibria of the closed-loop system

## Second equilibrium

$$x_1^* = 0, x_3^* = -\frac{c + k_3 K_B}{k_3} < 0.$$

This equilibrium is physiologically unfeasible, since the inhibitor serum level can not be negative.

# Equilibria of the closed-loop system

## Third equilibrium

$$x_3^* = -\frac{ED50(a-n)}{a-b-n}.$$

The physiologically interesting case is when  $a - n > 0$ , i.e. the tumor does not heal spontaneously. The equilibrium point for  $x_3^*$  is positive if and only if

$$a - b - n < 0.$$

It has been shown earlier that this is the condition for the drug to be effective against tumor.



# Equilibria of the closed-loop system

## Third equilibrium

$$x_1^* = \frac{x_{1,n}}{x_{1,d}}$$

with

$$\begin{aligned}x_{1,n} &= bED_{50}(a - n)(b(c + k_3K_B) \\ &\quad - a(c + k_3(-ED_{50} + K_B)) \\ &\quad + (c - ED_{50}k_3 + k_3K_B)n) \\ x_{1,d} &= (a - b - n)(ab_{\kappa} - bk_1 - b_{\kappa}n) \cdot \\ &\quad \cdot (a(ED_{50} - K_B) + bK_B \\ &\quad + (-ED_{50} + K_B)n).\end{aligned}$$

# Equilibria of the closed-loop system

## Third equilibrium

Taking into account the previous conditions, this equilibrium is positive if either

$$k_1 > b_{\kappa} \frac{a - n}{b}$$

$$k_3 > c \frac{a - b - n}{aED_{50} - aK_B + bK_B - ED_{50}n + K_Bn}$$

or

$$k_1 < b_{\kappa} \frac{a - n}{b}$$

$$k_3 < c \frac{a - b - n}{aED_{50} - aK_B + bK_B - ED_{50}n + K_Bn}.$$



# Equilibria of the closed-loop system

## Third equilibrium

If the Jacobian  $J$  is a  $2 \times 2$  matrix, then the eigenvalues of the Jacobian are

$$\lambda_{1,2} = \frac{\text{Tr}(J) \pm \sqrt{\text{Tr}(J)^2 - 4 \text{Det}(J)}}{2}.$$

In order to have eigenvalues with negative real parts (i.e., to guarantee that the equilibrium point is stable) the parameters should be chosen such that

$$\text{Tr}(J) < 0$$

$$\text{Det}(J) > 0.$$



# Equilibria of the closed-loop system

## Third equilibrium

The equilibrium is stable iff

$$k_1 > b_\kappa \frac{a - n}{b}$$

$$k_3 > \frac{\varphi}{\omega}$$

$$\begin{aligned} \varphi = & c(-a + b + n)^2(a^2 b_\kappa (ED_{50} - K_B) \\ & - b^2 k_1 K_B + 2ab_\kappa (-ED_{50} + K_B)n \\ & + b_\kappa (ED_{50} - K_B)n^2) \end{aligned}$$

$$\begin{aligned} \omega = & (a(ED_{50} - K_B) + bK_B \\ & + (-ED_{50} + K_B)n)^2(a^2 b_\kappa \\ & + b^2 k_1 - 2ab_\kappa n + b_\kappa n^2). \end{aligned}$$



## Equilibria of the closed-loop system

### Decreasing the third equilibrium tumor volume

$$x_1^* = \frac{x_{1,n}}{x_{1,d}}$$

$$\begin{aligned} \partial_{k_3} x_{1,n} &= bED_{50}(a-n)(bK_B - a(-ED_{50} + K_B)) \\ &\quad + (-ED_{50} + K_B)n > 0 \end{aligned}$$

Decreasing  $k_3$  decreases equilibrium tumor volume, however, the closed-loop system may become unstable.

### Control input

$$u = k_1 x_1 - k_3 x_3.$$

Decreasing  $k_3$  results in increasing control input.

## Equilibria of the closed-loop system

### Decreasing the third equilibrium tumor volume

$$x_1^* = \frac{x_{1,n}}{x_{1,d}}$$

$$\partial_{k_1} x_{1,d} = b(-a + b + n)(a(ED_{50} - K_B) + bK_B) + (-ED_{50} + K_B)n > 0$$

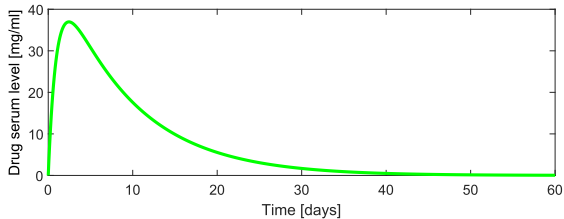
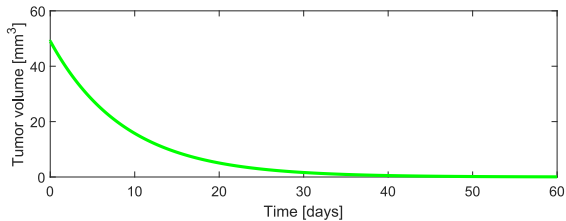
Increasing  $k_1$  means decreasing equilibrium tumor volume, no conflict with stability.

### Control input

$$u = k_1 x_1 - k_3 x_3.$$

Increasing  $k_1$  means increasing control input.

# Equilibria of the closed-loop system



Thank you for your attention!

## Contact:

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