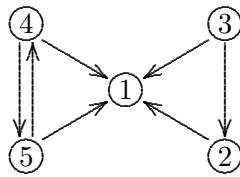
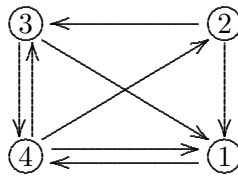


PageRank

1. Consider the following three graphs:

 G_1  G_2  G_3

- Determine the link matrices A_1 , A_2 and A_3 of the three graphs defined in the PageRank algorithm. (If there is a vertex with no outgoing arrow, modify the graph so that you add an arrow from this vertex to all vertices of the graph, including itself.)
- Find the solutions of the equation $\mathbf{x} = A_i \mathbf{x}$ for each i , to give a ranking of the pages/vertices of the graph.
- Use the modified matrix $\hat{A}_3 = (1 - p)A_3 + p\frac{1}{4}J$ to get a full ranking with $p = \frac{1}{4}$ and $p = \frac{1}{2}$, respectively.

Linear maps

- Which of the following sets form a vector space over \mathbb{R} ? Give a basis of the vector spaces.
 - 3×3 real upper triangular matrices with the usual operations;
 - invertible 2×2 real matrices;
 - polynomials of degree at most 4 which have -1 as one of their roots;
- Choose a basis in the subspace of \mathbb{R}^4 spanned by the vectors $\mathbf{v}_1 = (1, 2, 0, 1)$, $\mathbf{v}_2 = (0, -1, 1, -1)$, $\mathbf{v}_3 = (1, 0, 2, -1)$, $\mathbf{v}_4 = (0, 1, 1, 1)$, $\mathbf{v}_5 = (2, 3, 3, 1)$, and give the coordinate vectors of each \mathbf{v}_i with respect to this basis.
- Determine the matrices of the following linear maps with respect to the given basis or pair of bases:
 - rotation of the 3 dimensional space about the z axis by 90° , in the standard basis;
 - $p(x) \mapsto (xp(x))'$ in the space of real polynomials of degree at most 2, in the standard basis $\{1, x, x^2\}$;
 - $\mathbf{x} \mapsto A\mathbf{x}$, where $A = \begin{bmatrix} 1 & -1 \\ 4 & -3 \end{bmatrix}$, $\mathcal{B} = \{(1, 2), (1, 1)\}$;
 - $\varphi : \mathbb{R}^3 \rightarrow \mathbb{R}^3$, where $\varphi(1, 2, 1) = (0, 2, 1)$, $\varphi(1, 1, 1) = (1, 0, 0)$, $\varphi(1, 0, 0) = (-1, 0, 0)$, in the standard basis;
 - $\varphi : \mathbb{R}^2 \rightarrow \mathbb{R}^3$, $\varphi(x, y) = (x + y, y, x)$, in the pair of bases $\mathcal{B}_1 = \{(1, 1), (2, 0)\}$, $\mathcal{B}_2 = \{(1, 2, 1), (-1, 1, 0), (0, 1, 1)\}$;
 - orthogonal projection onto the plane $x - 2y + z = 0$, in the standard basis;
 - transposition of 2×2 real matrices, in the standard basis.
- Let A be the standard matrix of $f : (x, y, z) \mapsto (x + y - 2z, x + z, 2x + y - z, -x - z)$. Give bases for the null space of A (i.e. the kernel of f) and for the column space of A (i.e. the image of f).
- Find a linear transformation $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that
 - $0 \neq \text{Ker } f \subseteq \text{Im } f$;
 - $\text{Im } f$ is 2 dimensional, and f maps each vector of $\text{Im } f$ into itself.
- Prove that
 - $\text{rank}(AB) \leq \min\{\text{rank } A, \text{rank } B\}$, where $A \in K^{k \times m}$ és $B \in K^{m \times n}$;
 - $|\text{rank } A - \text{rank } B| \leq \text{rank}(A + B) \leq \text{rank } A + \text{rank } B$, where $A, B \in K^{m \times n}$.
 (*Hint: Prove that, considering the matrices as linear maps in the natural way, $\text{Im } AB \leq \text{Im } A$, $\text{Ker } AB \geq \text{Ker } B$ and $\text{Im}(A + B) \leq \text{span}(\text{Im } A, \text{Im } B)$.)*

8. Show that for any matrix $A \in K^{m \times n}$ and any invertible matrices $B \in K^{m \times m}$ and $C \in K^{n \times n}$, we have $\text{rank } BA = \text{rank } AC = \text{rank } A$.
9. Use Newton's interpolation to find a polynomial $f(x)$ of degree at most 3 such that $f(-1) = 0$, $f(0) = 1$, $f(2) = 1$ and $f(3) = -1$.

Eigenvectors, eigenvalues, diagonalization

10. Find the eigenvalues and eigenspaces of the following matrices. What is the action of the transformation $\mathbf{x} \mapsto D\mathbf{x}$ in \mathbb{R}^3 .

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad C = \begin{bmatrix} 4 & -4 & 1 \\ 1 & -1 & 0 \\ -2 & 4 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 3 & 1 & -3 \\ 0 & 1 & 0 \\ 2 & 1 & -2 \end{bmatrix}$$

11. Find the n 'th power of the matrix $A = \begin{bmatrix} 1 & -2 \\ -2 & 1 \end{bmatrix}$.
12. What are the eigenvalues and eigenvectors of the following linear transformations?
- Rotation of \mathbb{R}^3 by 90° about the z axis.
 - Projection of \mathbb{R}^2 on the line $y = x$ in the direction of the vector $(1, 0)$.
 - $f : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$ mapping every matrix A to $A + A^T$.
13. Show that every 3×3 real matrix has an eigenvector.
14. Prove that every eigenvector of A is an eigenvector of A^2 . Is the reverse statement true?

Euclidean spaces and their transformations

15. Write the vector \mathbf{b} as the sum of a vector which is orthogonal to \mathbf{a} and a vector which is parallel to \mathbf{a} if
- $\mathbf{a} = (1, -2, 0, 1)$, $\mathbf{b} = (3, 1, 1, 1)$;
 - $\mathbf{a} = (1 + i, 1 - i)$, $\mathbf{b} = (i, 3 - i)$.
16. Prove that the subset $\{(x_1, x_2, x_3, x_4, x_5) \mid x_1 + x_2 = x_4 + x_5\}$ is a hyperplane in \mathbb{R}^5 , and determine its normal vector. Calculate the reflection of $(1, 0, 0, 0, 0)$ to this hyperplane.
17. Give the standard matrix of the orthogonal projection and of the reflection on the hyperplane $x + y - z = 0$ in \mathbb{R}^3 .
18. Find the standard matrix of a reflection which maps the vector $(1, 2, -2)$ to $(3, 0, 0)$. (Hint: It is the reflection on the bisector plane of the line segment connecting the endpoints of the two vectors.)
19. Which of the following matrices are self-adjoint, unitary or normal?

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 2 & -1 \\ -2 & 0 & 3 \\ 1 & -3 & 0 \end{bmatrix} \quad C = \begin{bmatrix} i & i \\ i & -i \end{bmatrix} \quad D = \begin{bmatrix} 2 & 1 \\ 3 & 2 \end{bmatrix}$$

$$E = \begin{bmatrix} 1 & -1 \\ -1 & 3 \end{bmatrix} \quad F = \begin{bmatrix} -1 & 2+i \\ 2-i & -5 \end{bmatrix} \quad G = \begin{bmatrix} 1/3 & -2/3 & -2/3 \\ 2/3 & 2/3 & -1/3 \\ 2/3 & -1/3 & 2/3 \end{bmatrix} \quad H = \begin{bmatrix} 1 & i \\ 1+i & 0 \end{bmatrix}$$

Orthogonalization, QR decomposition

20. a) Orthogonalize the vectors $\mathbf{b}_1 = (0, 1, -1, 0)$, $\mathbf{b}_2 = (1, 1, 0, -1)$, $\mathbf{b}_3 = (1, 2, 1, 0)$ in \mathbb{R}^4 .
- b) Orthogonalize the vectors $\mathbf{b}_1 = (i, 1, 0)$ and $\mathbf{b}_2 = (1 + i, 0, i)$ in \mathbb{C}^3 , and then calculate the orthogonal projection of $\mathbf{v} = (1, 0, 0)$ on the subspace $\text{span}\{\mathbf{b}_1, \mathbf{b}_2\}$

21. Find a best approximate solution to the inconsistent system below, using the normal equations.

$$\begin{bmatrix} 1 & 2 & -1 \\ -1 & 1 & 1 \\ -1 & 0 & 1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$$

22. Prove that the normal system of equations $A^T A \mathbf{x} = A^T \mathbf{b}$ is consistent for any system $A \mathbf{x} = \mathbf{b}$.
23. Find the best approximate solution to the inconsistent system of equations below by first determining the QR decomposition of the coefficient matrix.

$$\begin{bmatrix} 1 & 0 & 5 \\ 0 & -2 & 0 \\ -1 & 4 & 3 \\ -1 & 0 & -1 \\ -1 & 0 & -1 \end{bmatrix} \mathbf{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

24. Consider the vectors $\mathbf{v}_1 = (1, 0, -1, 1)$, $\mathbf{v}_2 = (1, 0, 0, 2)$, $\mathbf{v}_3 = (0, 0, 1, 1)$ in \mathbb{R}^4 . Give an orthogonal basis of $W = \text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ and of W^\perp .
25. Use the reduced QR decomposition of the coefficient matrix A in the solution of problem 23 to construct the full QR decomposition.
26. Determine the matrix of the Householder reflection and the Givens rotation mapping the vector $(-3, 0, 4)$ to $(5, 0, 0)$.
27. Find the full QR decomposition of the matrix A by using Householder reflections, and use this to give a reduced QR decomposition.

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -2 \\ 2 & -6 \end{bmatrix}$$

28. Determine the QR decomposition of the matrix A , using Givens rotations, and in the end, if necessary, an extra reflection.

$$A = \begin{bmatrix} 0 & -1 & 1 \\ 3 & 3 & 0 \\ 4 & 4 & -5 \end{bmatrix}$$

Pseudoinverse

29. a) Show that for any matrices $A \in K^{m \times n}$ and $B \in K^{n \times m}$ the nonzero eigenvalues of $AB \in K^{m \times m}$ and $BA \in K^{n \times n}$ are the same.
- b) Calculate the rank and eigenvalues of AA^T and $A^T A$ for the matrix

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & 1 \end{bmatrix}.$$

30. Determine the pseudoinverses of the following matrices.

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}, \quad \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 & -1 \\ 2 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

31. Use the pseudoinverse calculated in problem 30 to find the smallest, best approximate solution of the system $y - z = 1$, $2x + y + z = 1$, $x + y = 0$.

43. Is $\lim_{k \rightarrow \infty} A^k$ convergent for the following matrices?

$$a) A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad b) A = \begin{bmatrix} 3/5 & 4/5 \\ -4/5 & 3/5 \end{bmatrix} \quad c) A = \begin{bmatrix} 0 & 1 \\ -1 & 2 \end{bmatrix} \quad d) A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & \frac{1}{2} \end{bmatrix}$$

Nonnegative matrices

44. Which of the following matrices are irreducible, primitive, or stochastic?

$$\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 2 & 0 \\ 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & 0 & 1/4 & 0 \\ 0 & 0 & 1/4 & 0 \\ 1 & 1 & 1/4 & 1 \\ 0 & 0 & 1/4 & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & 0 & 5 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \frac{1}{2} \cdot \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \quad \begin{bmatrix} 0 & 0 & 0 & 3 \\ 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

45. There is a flea on the number line, at first positioned randomly on any of the points 1, 2, 3 or 4. The flea changes its position in every second, always jumping to one of these four points. If it is on point 1 or 4 then it jumps to distance 1 with probability $\frac{2}{3}$, and to distance 2 with probability $\frac{1}{3}$. If it is on 2 or 3 then it jumps to one of the neighbouring numbers, each with probability $\frac{1}{2}$. What is the limit of the distribution of the position of the flea?