

1. Let $\mathbf{b} \in \mathbb{R}^m$ and all entries of $\mathbf{a} \in \mathbb{R}^m$ are 1. We consider $\mathbf{a}x = \mathbf{b}$ with unique real variable x . Let \hat{x} denote the least squares solution. Then

- (i) $\mathbf{a}^T \mathbf{a} \hat{x} = \mathbf{a}^T \mathbf{b}$ shows that \hat{x} is the average (mean) of the entries of \mathbf{b} ;
- (ii) $\|\mathbf{b} - \mathbf{a} \hat{x}\|^2$ is the variance of the entries of \mathbf{b} (its square root is the standard deviation);
- (iii) find the projection matrix P onto the line through \mathbf{a} .

2. True or false?

- (i) If Q is an orthogonal matrix then so is Q^{-1} .
- (ii) If an $m \times n$ matrix A has orthogonal columns then $\|A\mathbf{v}\| = \|\mathbf{v}\|$ for every vector $\mathbf{v} \in \mathbb{R}^n$.
- (iii) A has three orthogonal columns of length 1, 2 and 3 if and only if $A^T A$ is a diagonal matrix with diagonal entries 1, 4 and 9.
- (iv) If an orthogonal matrix is lower triangular then it is diagonal.
- (v) The determinant of $I + A$ is $1 + |A|$.

3. Let $b_1 = 0, b_2 = 8, b_3 = 8, b_4 = 20$ be the measurements at times $t_1 = 0, t_2 = 1, t_3 = 3, t_4 = 4$. Find the best straight line approximating these points on the plane, by determining and solving the normal equation $A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$. What is the minimum (total) error?

4. Let \mathbf{e} be the error vector for a projection problem. Which is \mathbf{e} perpendicular to: $\mathbf{b}, \hat{\mathbf{x}}, \mathbf{e}, \mathbf{p}$? Show that $\|\mathbf{e}\|^2 = \mathbf{e}^T \mathbf{b} = \mathbf{b}^T \mathbf{b} - \mathbf{b}^T \mathbf{p}$.

5. Perform the Gram-Schmidt orthogonalisation algorithm for the vectors $\mathbf{a}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \mathbf{a}_2 = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$. Do the

same for the columns of $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$.

6. **HW** Let $x + y - 2z = 0$ describe a plane \mathcal{P} in the space \mathbb{R}^3 . Find two orthogonal vectors in \mathcal{P} and make them orthonormal. Extend it to an orthonormal basis of \mathbb{R}^3 .

7. Determine the following determinants:

$$\begin{vmatrix} 1 & 2 & 3 \\ 2 & 2 & 3 \\ 3 & 3 & 3 \end{vmatrix}, \quad \begin{vmatrix} 1 & a & a^2 \\ a & 1 & a \\ a^2 & a & 1 \end{vmatrix}, \quad \begin{vmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{vmatrix}, \quad \det \left([1 \ 2 \ 3] \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \right).$$

8. Find the determinant of rotations and reflections:

$$Q_1 = \begin{bmatrix} \cos \vartheta & -\sin \vartheta \\ \sin \vartheta & \cos \vartheta \end{bmatrix}, \quad Q_2 = \begin{bmatrix} \cos 2\vartheta & -\sin 2\vartheta \\ -\sin 2\vartheta & -\cos 2\vartheta \end{bmatrix}.$$

9. Observe that 7 divides 343, 147 and 504. Surprise surprise, 7 divides the following determinant. Why?

$$\begin{vmatrix} 3 & 4 & 3 \\ 1 & 4 & 7 \\ 5 & 0 & 4 \end{vmatrix}.$$

10. What is the determinant of a projection matrix?