

MULTIVARIATE STATISTICS, Lesson 7.

Multivariate statistical methods: reduction of dimensionality

- **Principal component analysis.** Model: $\mathbf{X} = \mathbf{U}\mathbf{Y} + \mathbf{m}$, where $\mathbf{X} \sim \mathcal{N}_p(\mathbf{m}, \mathbf{C})$, $\mathbf{Y} \sim \mathcal{N}_p(\mathbf{0}, \mathbf{D})$, where \mathbf{U} is an appropriately chosen $p \times p$ orthogonal, while \mathbf{D} is diagonal matrix.

1. *Proposition:* \mathbf{U} contains the eigenvectors $\mathbf{u}_1, \dots, \mathbf{u}_p$ of \mathbf{C} columnwise corresponding to the eigenvalues $\lambda_1 \geq \dots \geq \lambda_p$.
2. *Definition:* $Y_i = \mathbf{u}_i^T(\mathbf{X} - \mathbf{m})$ is the i th **principal component** with variance λ_i ($i = 1, \dots, p$).
3. *Remark:* The variance of Y_i is λ_i , and the total variance of the principal components is equal to the total variance of the original X_i 's.
4. *Theorem:* The variance of Y_1 is the largest possible among the variances of linear combinations $\mathbf{v}^T(\mathbf{X} - \mathbf{m})$ subject to $\|\mathbf{v}\| = 1$. In general: the variance of Y_k is the largest possible among the variances of linear combinations $\mathbf{v}^T(\mathbf{X} - \mathbf{m})$ that are uncorrelated with Y_1, \dots, Y_{k-1} (subject to $\|\mathbf{v}\| = 1$), $k = 2, \dots, p$.
5. *Stronger Theorem:* The k -dimensional vector with components $(Y_1, \dots, Y_k, 0, \dots, 0)$ gives the best k -dimensional approximation of $\mathbf{X} \sim \mathcal{N}_p(\mathbf{0}, \mathbf{C})$ in the following sense: the minimum of $\mathbb{E}\|\mathbf{X} - \mathbf{A}\mathbf{X}\|$ with a $p \times p$ matrix \mathbf{A} of rank k is attained by the projection onto the k -dimensional subspace spanned by $\mathbf{u}_1, \dots, \mathbf{u}_k$ for any $k = 1, \dots, p$.
6. *Sequential testing of hypotheses* for the number of relevant principal components. Based on the eigenvalues of the sample covariance matrix, for testing

$$H_k : \lambda_{k+1} = \dots = \lambda_{p-1} = \lambda_p, \quad k = 0, 1, \dots, p-1$$

the transformed test statistic (obtained by likelihood ratio test)

$$-2 \ln \lambda_n = n(p-k) \ln \frac{a}{g}, \quad a = \frac{\hat{\lambda}_{k+1} + \dots + \hat{\lambda}_p}{p-k}, \quad g = (\hat{\lambda}_{k+1} \dots \hat{\lambda}_p)^{\frac{1}{p-k}}$$

is used ($\hat{\lambda}_i$'s are the eigenvalues of the empirical covariance matrix) that for large n approximately follows $\chi^2(\frac{1}{2}(p-k+2)(p-k-1))$ -distribution.

- **Factor analysis.** Model: $\mathbf{X} = \mathbf{A}\mathbf{f} + \mathbf{e} + \mathbf{m}$, where $\mathbf{X} \sim \mathcal{N}_p(\mathbf{m}, \mathbf{C})$, \mathbf{A} is $p \times k$ matrix, $\mathbf{f} \sim \mathcal{N}_k(\mathbf{0}, \mathbf{I}_k)$ is the **common factor** and the components of $\mathbf{e} \sim \mathcal{N}_p(\mathbf{0}, \mathbf{D})$ are the **individual factors** of the variables with variances along the main diagonal of the diagonal matrix \mathbf{D} . Further, \mathbf{f} and \mathbf{e} are independent. If multivariate normality is not postulated, the conditions

$$\mathbb{E}\mathbf{f} = \mathbf{0}, \quad \mathbb{E}\mathbf{f}\mathbf{f}^T = \mathbf{I}_k, \quad \mathbb{E}\mathbf{e} = \mathbf{0}, \quad \mathbb{E}\mathbf{e}\mathbf{e}^T = \mathbf{D}, \quad \mathbb{E}\mathbf{f}\mathbf{e}^T = \mathbf{0} \text{ matrix}$$

are used. For the coordinates and variances of X_i 's:

$$X_i = \sum_{j=1}^k a_{ij} f_j + e_i + \mu_i, \quad c_{ii} = \sum_{j=1}^k a_{ij}^2 + d_{ii} \quad (= 1, \dots, p).$$

1. *Definition:* $\sum_{j=1}^k a_{ij}^2$ is called *communality* of X_i ($i = 1, \dots, p$), and the entries of \mathbf{A} are called *factor loadings*.

2. *Identification*: we have to solve the matrix equation $\mathbf{C} = \mathbf{A}\mathbf{A}^T + \mathbf{D}$. The solution may exist for $k \geq (2p + 1 - \sqrt{8p + 1})/2$, and it is unique up to orthogonal rotation (if \mathbf{A} is solution, $\mathbf{A}\mathbf{Q}$ is also solution with any $k \times k$ orthogonal matrix \mathbf{Q}).
3. *ML factor analysis* (if multivariate normality is postulated): Maximize the multivariate normal likelihood function

$$-\frac{1}{2}n \ln |\mathbf{C}| - \frac{1}{2}n \text{tr } \mathbf{C}^{-1} \hat{\mathbf{C}} + c$$

with respect to \mathbf{A}, \mathbf{D} subject to $\mathbf{C} = \mathbf{A}\mathbf{A}^T + \mathbf{D}$; or equivalently, find the minimum of

$$F(\mathbf{A}, \mathbf{D}) = \ln |\mathbf{A}\mathbf{A}^T + \mathbf{D}| + \text{tr } (\mathbf{A}\mathbf{A}^T + \mathbf{D})^{-1} \hat{\mathbf{C}}$$

that, after differentiating, gives the model equations:

$$\frac{\partial F}{\partial \mathbf{A}} = \mathbf{C}^{-1}(\mathbf{C} - \hat{\mathbf{C}})\mathbf{C}^{-1}\mathbf{A} = \mathbf{0}, \quad \frac{\partial F}{\partial \mathbf{D}} = \text{diag} [\mathbf{C}^{-1}(\mathbf{C} - \hat{\mathbf{C}})\mathbf{C}^{-1}] = \mathbf{0}.$$

For the solution, algorithms based on numeric iteration are at our disposal.

4. *Principal component factor analysis*: Retain the first k transformed principal components, where there is a remarkable spectral gap between the k th and $(k+1)$ th eigenvalues of the sample covariance (or correlation) matrix. We use the transformation:

$$\mathbf{U}\mathbf{Y} = (\mathbf{U}\Lambda^{1/2})(\Lambda^{-1/2}\mathbf{Y}),$$

where \mathbf{f} will consist of the first k components of $\Lambda^{-1/2}\mathbf{Y}$.

5. Rotation of factor loadings (VARIMAX).
6. See BMDP outputs after processing real world data.