

(1)

Stochastic Processes / M6006 Problem set 3 - Solutions

3.1 $0 = \Delta_0 < \Delta_1 < \dots < \Delta_n = t$

$$\max_{0 \leq i < n} |\Delta_{i+1} - \Delta_i| \rightarrow 0 \text{ as } n \rightarrow \infty$$

$$V(t)B(t) - V(0)B(0) =$$

$$\sum_{i=0}^{n-1} (V(\Delta_{i+1})B(\Delta_{i+1}) - V(\Delta_i)B(\Delta_i)) =$$

$$\sum_{i=0}^{n-1} V(\Delta_i)(B(\Delta_{i+1}) - B(\Delta_i)) +$$

$$\sum_{i=0}^{n-1} B(\Delta_{i+1}) (V(\Delta_{i+1}) - V(\Delta_i)) = \text{*} \text{bura page}$$
$$= V'(\Delta_{i+1}^*) (\Delta_{i+1} - \Delta_i) \text{*}$$

will show $\Delta_i \leq \Delta_{i+1}^* \leq \Delta_{i+1}$

(2)

$$V(t)B(t) - V(0)B(0) =$$

$$\sum_{i=0}^{n-1} V(\Delta_i) (B(\Delta_{i+1}) - B(\Delta_i)) \} \xrightarrow{\text{Ito}} \int_0^t V(s) dB(s)$$

$$+ \sum_{i=0}^{n-1} B(\Delta_{i+1}) V'(\Delta_{i+1}^*) (\Delta_{i+1} - \Delta_i) \} \xrightarrow{\text{Riemann}} \int_0^t B(s) V'(s) ds$$

$$= \int_0^t V(s) dB(s) + \int_0^t B(s) V'(s) ds$$

(3.2) $B(t)^2 - B(0)^2 =$

$$\sum_{i=0}^{n-1} (B(\Delta_{i+1})^2 - B(\Delta_i)^2) = \xrightarrow{\text{Ito}} 2 \int_0^t B(s) dB(s)$$

$$2 \sum_{i=0}^{n-1} B(\Delta_i) (B(\Delta_{i+1}) - B(\Delta_i)) +$$

$$+ \sum_{i=1}^{n-1} (B(\Delta_{i+1}) - B(\Delta_i))^2 \xrightarrow{\text{quadr. var.}} t$$

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$$B(t)^3 - B(0)^3 =$$

$$\sum_{i=0}^{n-1} \left(B(\Delta_{i+1})^3 - B(\Delta_i)^3 \right) =$$

$$3 \sum_{i=0}^{n-1} B(\Delta_i)^2 (B(\Delta_{i+1}) - B(\Delta_i)) \xrightarrow{\text{Itô}} 3 \int_0^t B(s)^2 dB(s)$$

$$+ 3 \sum_{i=0}^{n-1} B(\Delta_i) (B(\Delta_{i+1}) - B(\Delta_i))^2 \xrightarrow{\text{Itô}} 3 \int_0^t B(s) ds$$

$$+ \sum_{i=0}^{n-1} (B(\Delta_{i+1}) - B(\Delta_i))^3 \xrightarrow{\text{Itô}} 0$$

$$\mathbb{E} \left\{ \sum_{i=0}^{n-1} B(\Delta_i) \left((B(\Delta_{i+1}) - B(\Delta_i))^2 - (\Delta_{i+1} - \Delta_i) \right) \right\}^2 =$$

$$\sum_{i=0}^{n-1} \mathbb{E} \left(B(\Delta_i)^2 \left((B(\Delta_{i+1}) - B(\Delta_i))^2 - (\Delta_{i+1} - \Delta_i) \right)^2 \right) +$$

$$2 \sum_{i=0}^{n-1} \sum_{j=i+1}^{n-1} \mathbb{E} \left(B(\Delta_i) B(\Delta_j) \left((B(\Delta_{i+1}) - B(\Delta_i))^2 - (\Delta_{i+1} - \Delta_i) \right) \left((B(\Delta_{j+1}) - B(\Delta_j))^2 - (\Delta_{j+1} - \Delta_j) \right) \right)$$

(4)

$$= C \sum_{i=0}^{n-1} \Delta_i (\Delta_{i+1} - \Delta_i)^2 \rightarrow 0. \quad \checkmark$$

the other term done similarly.

This is problem (2.4) now, Go further down for (3.3)

(2.4)
(a)

$$E(B(t) + t \mid \mathcal{F}_\Delta^B) = B(\Delta) + t \neq B(\Delta) + \Delta$$

(not) martingale

$$(b) \quad E(B(t)^2 \mid \mathcal{F}_\Delta^B) = B(\Delta)^2 + (t - \Delta) \neq B(\Delta)^2$$

(not) martingale

$$(c) \quad E\left(t^2 B(t) - 2 \int_0^t B(r) dr \mid \mathcal{F}_\Delta^B\right) = t^2 B(\Delta) - 2 \int_0^\Delta (t - r) B(r) dr - 2 \int_\Delta^t r B(\Delta) dr$$

(7)

$$= \Delta^2 B(\Delta) - 2 \int_0^\Delta r B(r) dr$$

this one (is) a martingale

(d) $E(B_1(t) B_2(t) | \mathcal{F}_\Delta^B) = B_1(\Delta) B_2(\Delta)$

it (is) a martingale

3.3

$$\xi := C - D + \int_0^T (v(s) - w(s)) dB(s)$$

$$\xi = 0$$

But

$$E(\xi) = C - D$$

$$\text{Var}(\xi) = \int_0^T E(|v(s) - w(s)|^2) ds$$

both must vanish. Hence the claim.

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$$\mathbb{E}(Y_\alpha(t)^2) = \int_0^t (t-s)^{-2\alpha} ds < \infty$$

$$\text{if } \alpha < \frac{1}{2}$$

$$0 < s < t$$

$$\mathbb{E}(Y_\alpha(s)Y_\alpha(t)) =$$

$$\mathbb{E}\left(\int_0^s (s-u)^{-\alpha} dB(u) \int_0^t (t-r)^{-\alpha} dB(r)\right) =$$

$$\int_0^s (s-u)^{-\alpha} (t-u)^{-\alpha} du =$$

$$s^{1-2\alpha} \int_0^1 (1-u)^{-\alpha} \left(\frac{t}{s} - u\right)^{-\alpha} du.$$

Stochastic Processes - Problem Set 3 continued ^④

Solutions

3.5

$$(a) \quad dX(t) = 2B(t)dB(t) + dt$$

$$X(0) = 0$$

$$\mu(\Delta) = 1$$

$$\sigma(\Delta) = 2B(\Delta)$$

$$(b) \quad dX(t) = dt + e^{B(t)}dB(t) + \frac{1}{2}e^{B(t)}dt$$

$$X(0) = 2, \quad \mu(\Delta) = 1 + \frac{1}{2}e^{B(\Delta)}, \quad \sigma(\Delta) = e^{B(\Delta)}$$

$$(c) \quad dX(t) = 2B_1(t)dB_1(t) + 2B_2(t)dB_2(t) \\ + dt + dt$$

$$X(0) = 0, \quad \mu(\Delta) = 2; \quad \sigma(\Delta) = \begin{pmatrix} 2B_1(\Delta) \\ 2B_2(\Delta) \end{pmatrix}$$

②

$$(d) \quad dX(t) = \begin{pmatrix} dt \\ dB(t) \end{pmatrix}$$

$$X(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \quad \mu(\Delta) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}; \quad \nu(\Delta) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$(e) \quad dX(t) = \begin{pmatrix} dB_1(t) + dB_2(t) + dB_3(t) \\ 2B_1(t)dB_2(t) + dt - B_1(t)dB_3(t) - B_3(t)dB_1(t) \end{pmatrix}$$

$$X(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}; \quad \mu(\Delta) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\nu(\Delta) = \begin{pmatrix} 1 & 1 & 1 \\ -B_3(\Delta) & 2B_2(\Delta) & -B_1(\Delta) \end{pmatrix}$$

$$\textcircled{3.6} \quad d(B(t)^3) = 3B(t)^2 dB(t) + 3B(t) dt$$

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$$Y(t) = \int_0^t \theta(s) \cdot dB(s) - \frac{1}{2} \int_0^t |\theta(s)|^2 ds$$

$$Z(t) = \exp(Y(t))$$

$$dZ(t) = \exp(Y(t)) dY(t) + \frac{1}{2} \exp(Y(t)) (dY(t))^2$$

$$\underbrace{\hspace{10em}}_{= |\theta(t)|^2 dt}$$

$$= \dots = \exp(Y(t)) \theta(t) \cdot dB(t)$$

$$= Z(t) \theta(t) \cdot dB(t)$$

(b) thus

$$Z(t) = \int_0^t Z(s) \theta(s) \cdot dB(s)$$

is an Itô integral \implies martingale.

3.8

$$d(B^{k+2}(t)) = (k+2) B(t)^{k+1} dB(t) + \frac{(k+2)(k+1)}{2} B(t)^k dt$$

$$B(t)^{k+2} = (k+2) \int_0^t B(s)^{k+1} dB(s) + \frac{(k+2)(k+1)}{2} \int_0^t B(s)^k ds$$

Hence

$$E(B(t)^{k+2}) = (k+2) E \left(\int_0^t B(s)^{k+1} dB(s) \right) + \frac{(k+2)(k+1)}{2} \int_0^t E(B(s)^k) ds$$

= 0

Hence $E(B(t)^{k+2}) = \frac{(k+2)(k+1)}{2} \int_0^t E(B(s)^k) ds$

Hence $E(B(t)^{2k+1}) = 0 \quad \forall k$

$$E(B(t)^2) = t$$

$$E(B(t)^4) = \frac{4 \cdot 3}{2} \int_0^t s ds = 3t^2$$

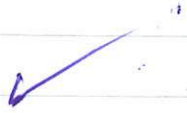
$$E(B(t)^6) = \frac{6 \cdot 5}{2} \int_0^t 3 \cdot s^2 ds = 15t^3$$

$$E(B(t)^{2k}) = \frac{(2k)!}{2^k k!} \cdot t^k$$

Induction

$$E(B(t)^{2(k+1)}) = \frac{2k!}{2^k k!} \cdot \frac{(2k+2)(2k+1)}{2} \int_0^t s^k ds$$

$$= \frac{2(k+1)!}{2^{k+1} (k+1)!} t^{k+1}$$



3.9

$$dX(t) = e^{(\alpha B(t) + rt)} \cdot (\alpha dB(t) + r dt)$$

$$+ \frac{1}{2} e^{\alpha B(t) + rt} \cdot (\alpha dB(t) + r dt)^2 =$$

$$= \dots = (r + \frac{\alpha^2}{2}) X(t) dt + \alpha X(t) dB(t)$$

3.10

(12)

$$dM(t) = 2X(t) \cdot dX(t) + |dX(t)|^2 - \text{tr}(\nu(t) \nu(t)^T) dt$$

$$= 2X(t) \cdot \nu(t) dB(t)$$

$$M(t) = M(0) + 2 \int_0^t X(s) \cdot \nu(s) dB(s)$$

is an Itô integral
Hence: a martingale

3.11

$$(a) dX(t) = \frac{1}{2} e^{t/2} \cos B(t) dt$$

$$- e^{t/2} \sin B(t) dB(t)$$

$$- \frac{1}{2} e^{t/2} \cos B(t) \underbrace{(dB(t))^2}_{dt}$$

$$= - e^{t/2} \sin B(t) dB(t) \checkmark$$

(b) very similar

$$\begin{aligned}
(c) \quad dX(t) &= \left(1 - \frac{1}{2}(B(t) + t)\right) e^{-(B(t) + t/2)} dt \\
&+ \left(1 - (B(t) + t)\right) e^{-(B(t) + t/2)} dB(t) \\
&- \frac{1}{2} \left(1 + 1 - B(t) - t\right) e^{-(B(t) + t/2)} \left(dB(t)\right)^2 \\
&= \left(1 - B(t) - t\right) e^{-(B(t) + t/2)} dB(t)
\end{aligned}$$

3.12

$$dX(t) = u(t)dt + dB(t)$$

$$dM(t) = -M(t) u(t) \cdot dB(t)$$

$$\begin{aligned}
dY(t) &= X(t) dM(t) + M(t) dX(t) \\
&+ \frac{1}{2} dX(t) dM(t) =
\end{aligned}$$

$$\begin{aligned}
&= -X(t)M(t)u(t)dB(t) + \\
&\quad M(t)u(t)dt + M(t)dB(t) + \\
&\quad \underbrace{(u(t)dt + dB(t))(-M(t)u(t)dB(t))}_{=-M(t)u(t)dt} \\
&= (M(t) - M(t)X(t)u(t))dB(t)
\end{aligned}$$

3.13

(a) $X = \int_0^T dB(s)$

(b) $X = \int_0^T B(s)ds = \int_0^T (T-s)dB(s)$

(c) $X - B(T)^2 = T + 2 \int_0^T B(s)dB(s)$

(15)

$$(d) X = B(T)^3 = 3 \int_0^T (B(s)^2 + T-s) dB(s)$$

$$(e) e^{B(T) - \frac{T}{2}} = A + \int_0^T e^{B(s) - \frac{s}{2}} dB(s)$$

$$e^{B(T)} = e^{\frac{T}{2}} + \int_0^T e^{B(s) + \frac{T-s}{2}} dB(s)$$

$$(f) d e^{\frac{t}{2}} \sin B(t) = e^{\frac{t}{2}} \cos B(t) dB(t)$$

$$\sin B(T) = \int_0^T e^{(t-T)/2} \cos B(t) dB(t)$$

3/4

$$\begin{aligned} dX(t) &= \left(X^{1/3} + \frac{1}{3} B(t) \right)^2 dB(t) + \\ &+ \frac{1}{3} \left(X^{1/3} + \frac{1}{3} B(t) \right) dt \\ &= |X(t)|^{2/3} dB(t) + \frac{1}{3} \operatorname{sgn}(X(t)) |X(t)|^{1/3} dt \end{aligned}$$

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