

Problem Set 7 - Solutions

(1)

(7.1) Assume first that \mathcal{G} is discrete with partition elements $(G_k)_{k=1,2,\dots}$

Then

$$E_Q(X|G_k) = \frac{\int_{G_k} X(\omega) dQ(\omega)}{\int_{G_k} dQ(\omega)} =$$

$$= \frac{\int_{G_k} X(\omega) g(\omega) dP(\omega)}{\int_{G_k} g(\omega) dP(\omega)} \cdot \frac{P(G_k)}{P(G_k)}$$

$$= \frac{E_P(X \cdot g | G_k)}{E_P(g | G_k)}$$

General case (conditional expectation a la
Kolmogorov) ②

let $Z \in \mathcal{L}^\infty(\Omega, \mathcal{G}, \mathbb{P})$ (bdd, \mathcal{G} -measurable)

$$\mathbb{E}_Q(Z \cdot \mathbb{E}_Q(X|\mathcal{G})) = \mathbb{E}_Q(ZX)$$

by def. of conditional expectation

$$= \mathbb{E}_P(\mathcal{S}Z \cdot X)$$

$$\mathbb{E}_Q\left(Z \cdot \frac{\mathbb{E}_P(\mathcal{S}X|\mathcal{G})}{\mathbb{E}_P(\mathcal{S}|\mathcal{G})}\right) = \mathbb{E}_P\left(\mathcal{S}Z \frac{\mathbb{E}_P(\mathcal{S}X|\mathcal{G})}{\mathbb{E}_P(\mathcal{S}|\mathcal{G})}\right)$$

$$= \mathbb{E}_P\left(\mathcal{S} \frac{\mathbb{E}_P(\mathcal{S}ZX|\mathcal{G})}{\mathbb{E}_P(\mathcal{S}|\mathcal{G})}\right) =$$

$$= \mathbb{E}_P\left(\mathbb{E}_P(\mathcal{S}|\mathcal{G}) \cdot \frac{\mathbb{E}_P(\mathcal{S}ZX|\mathcal{G})}{\mathbb{E}_P(\mathcal{S}|\mathcal{G})}\right) =$$

$$= \mathbb{E}_P\left(\mathbb{E}_P(\mathcal{S}ZX|\mathcal{G})\right) = \mathbb{E}_P(\mathcal{S}ZX) \quad \checkmark$$

③

$$\textcircled{7.2} \Omega_n = \{0, 1\}^n$$

$$T=0, H=1$$

$$P_n(\omega_1 \omega_2 \dots \omega_n) = \left(\frac{2}{3}\right)^{\sum_{k=1}^n \omega_k} \left(\frac{1}{3}\right)^{\sum_{k=1}^n (1-\omega_k)}$$

$$Q_n(\omega_1 \omega_2 \dots \omega_n) = \left(\frac{1}{2}\right)^n$$

$$\frac{dQ_n}{dP_n}(\underline{\omega}) = Z_n(\underline{\omega}) = \left(\frac{3}{2}\right)^n \cdot \left(\frac{1}{2}\right)^{-\sum_{k=1}^n \omega_k}$$

$$Z_{m+1} = Z_m \cdot \frac{3}{2} \cdot 2^{-\omega_{m+1}}$$

\textcircled{a} given (Z_1, Z_2, \dots, Z_m) , $Z_{m+1} = \begin{cases} Z_m \cdot \frac{3}{2} & \text{with prob. } \frac{1}{3} \\ Z_m \cdot \frac{3}{4} & \text{with prob. } \frac{2}{3} \end{cases}$
 under P

$$\textcircled{b} E_Q(X | \mathcal{F}_2) = \omega_1 + \omega_2 + \frac{1}{2}$$

~~$$E_P(X \cdot Z | \mathcal{F}_2) = E_P(\omega_1 + \omega_2 + \omega_3) \cdot \frac{3}{2}$$~~

$$E_P\left(X \cdot \frac{Z_3}{Z_2} \mid \mathcal{F}_2\right) = E_P\left((\omega_1 + \omega_2 + \omega_3) \cdot \frac{3}{2} \cdot 2^{-\omega_3} \mid \mathcal{F}_2\right)$$

(4)

$$= \frac{3}{2} (\omega_1 + \omega_2) \underbrace{E_P(2^{-\omega_3} | \mathcal{F}_2)}_{= 2/3} + \frac{3}{2} \underbrace{E_P(\omega_3 2^{-\omega_3} | \mathcal{F}_2)}_{= 1/3} = \omega_1 + \omega_2 + \frac{1}{2} \checkmark$$

(c) ... interpretation ...

(7.3) (a) Follows from Girsanov

$$X(t) := F(t) + B(t)$$

$$E\left(\Phi(X(u): 0 \leq u \leq T)\right) =$$

$$E\left(\Phi(B(u): 0 \leq u \leq T) \exp\left(\int_0^T f(u) dB(u) - \frac{1}{2} \int_0^T |f(u)|^2 du\right)\right)$$

(b) if $\int_0^T |f(u)|^2 = \infty$ then the R-N derivative doesn't exist

7.4

a

$$dY(t) = \underbrace{\begin{pmatrix} 2 \\ 4 \end{pmatrix}}_{\mu} dt + \underbrace{\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}}_{\nu} \begin{pmatrix} dB_1(t) \\ dB_2(t) \end{pmatrix}$$

$$r = \nu^{-1} \mu = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

$$M(t) = \exp \{ -3B_1(t) + B_2(t) - 5t \}$$

$$dQ_t = M(t) dP_t$$

b

$$dY(t) = \underbrace{\begin{pmatrix} 0 \\ 1 \end{pmatrix}}_{\mu} dt + \underbrace{\begin{pmatrix} 1 & 3 \\ -1 & -2 \end{pmatrix}}_{\nu} \begin{pmatrix} dB_1(t) \\ dB_2(t) \end{pmatrix}$$

$$r = \nu^{-1} \mu = \begin{pmatrix} -2 & -3 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

$$M(t) = \exp \{ 3B_1(t) - B_2(t) - 5t \}$$

$$dQ_t = M(t) dP_t$$

6

$$\textcircled{FS} (\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$$

$$t \mapsto B(t) \in \mathbb{R}^n \quad (\mathcal{F}_t)_t - \text{B.M.}$$

$$M(t) := \exp \left\{ \int_0^t b(B(u)) \cdot dB(u) - \frac{1}{2} \int_0^t |b(B(u))|^2 du \right\}$$

$$dQ_t := M(t) d\mathbb{P}$$

then: under the measure Q_T

$$t \mapsto X(t) := B(t)$$

is weak solution of

$$dX(t) = b(X(t)) dt + d\hat{B}(t)$$

where $d\hat{B}(t) = dB(t) - b(B(t)) dt$

is BM under Q .

7.6

$$Y(t) = B(t) + \kappa t$$

$$M(t) = \exp \left\{ -B(t) - \frac{\kappa t}{2} \right\}$$

$$d\mathbb{Q}_t = M(t) d\mathbb{P}_t$$

$t \mapsto Y(t)$ - is drifted BM under \mathbb{P}

- is standard BM under \mathbb{Q}

\mathbb{Q}_∞ and \mathbb{P}_∞ are mutually singular

7.7

$$\mathbb{P}(X(t) > M) > 0$$



$$\mathbb{Q}(X(t) > M) > 0$$

=

$$\mathbb{P}(B(t) > M)$$

7.8 $h \in C^2(\mathbb{R}^n)$

$$dX(t) = \nabla h(X(t)) dt + dB(t), \quad X(0) = x$$

$t \mapsto X(t)$ strong sol.

$$M(t) = \exp \left\{ - \int_0^t \nabla h(X(u)) \cdot dB(u) - \frac{1}{2} \int_0^t |\nabla h(X(u))|^2 du \right\}$$

$$= \exp \left\{ - \int_0^t \nabla h(X(u)) \cdot dX(u) + \frac{1}{2} \int_0^t |\nabla h(X(u))|^2 du \right\}$$

a

$$E_x(f(X(t))) = E_x(M(t) M(t)^{-1} f(X(t)))$$

Girsanov $= E_x \left(e^{\int_0^t \nabla h(\hat{B}(u)) \cdot d\hat{B}(u) - \frac{1}{2} \int_0^t |\nabla h(\hat{B}(u))|^2 du} f(\hat{B}(t)) \right)$

$$\stackrel{It\hat{o}}{=} e^{-h(x)} E_x \left(e^{\int_0^t \left(-\frac{1}{2} |\nabla h(\hat{B}(u))|^2 + \Delta h(\hat{B}(u)) \right) du} e^{h(\hat{B}(t))} f(\hat{B}(t)) \right)$$

$$N(t, x) :=$$

(b) by Feynman-Kac formula: (9)

$N(t, x) :=$

$$E_x \left(e^{-\frac{1}{2} \int_0^t (Vh(B(u)))^2 + \Delta h(B(u)) du} e^{h(B(t))} \right) e^{f(B(t))}$$

is the unique bdd. solution of the initial value problem

$$\begin{cases} \frac{\partial N}{\partial t}(t, x) = \frac{1}{2} \Delta N(t, x) - V(x) N(t, x) \\ N(0, x) = e^{h(x)} f(x) \end{cases}$$