## Analysis of fractional diffusion problems

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 or  $\partial_{\nu} u \mid_{\partial\Omega} = 0$ 

• if  $\mathscr{X} = \mathbb{R}^d$ 

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- $\Delta^{\alpha}$  is a nonlocal operator, it is hard to define in nonhomogeneous cases.
- More equivalent formulations in  $L^p$ ,  $C_0$ ,  $C_{bu}$  spaces.

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#### Equivalent formulations in $\mathbb{R}^d$

Let  $\mathscr L$  be  $-(-\Delta)^{lpha/2}$  in  $\mathbb R^d$ .

- Fourier definition:  $\mathscr{F}(\mathscr{L}f)(\xi) = -|\xi|^{\alpha} \mathscr{L}f(\xi)$
- distributional definition:  $\int_{\mathbb{R}^d} \mathscr{L}f(y) \varphi(y) dy = \int_{\mathbb{R}^d} f(y) \mathscr{L}\varphi(y) dy$

• Bochner's definition: 
$$\mathscr{L}f = rac{1}{\gamma(-lpha/2)}\int_0^\infty (e^{t\Delta}f-f)t^{-1-lpha/2}dt$$

- Balakrishnan's definition:  $\mathscr{L}f = \frac{\sin(\alpha\pi/2)}{\pi} \int_0^\infty \Delta(sI \Delta)^{-1} f s^{\alpha/2 1} ds$
- singular integral definition:  $\mathscr{L}f = \lim_{r \to 0+} \frac{2^{\alpha}\gamma((d+\alpha)/2)}{\pi^{d/2}|\gamma(-\alpha/2)|} \int_{\mathbb{R}^d \setminus B(x,r)} \frac{f(\cdot+z)-f(\cdot)}{|z|^{d+\alpha}} dz$

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### Spectral definition in bounded domain

On an arbitrary Lipschitz domain  $(-\Delta)^{-1}$  with homogeneous boundary conditions can be recognized as a  $L_2(\Omega) \to H_0^1(\Omega)$  positive, self-adjoint, compact operator, and its eigenfunctions  $\{\omega_j\}_{j\in\mathbb{N}}$  make a complete system with eigenvalues  $\{\lambda_j\}_{j\in\mathbb{N}}$ . We can define

$$((-\Delta)^{-1})^lpha:L_2(\Omega) o L_2(\Omega)$$

for  $0 \le \alpha \le 1$  for  $u = \sum_{j \in \mathbb{N}} u_j \omega_j$  with $((-\Delta)^{-1})^{\alpha} u = \sum_{i \in \mathbb{N}} \lambda_j^{\alpha} u_j \omega_j.$ 

This also shows that the equation is well posed in this case.

Maros Gábor

#### Matrix transformation method for finite elements

Instead of constructing the appropriate bilinear form, we define directly the stiffness matrix corresponding to  $(-\Delta)^{\alpha}$  by taking the  $\alpha$  power of  $A_h$ , the stiffness matrix corresponding to  $-\Delta$ , for arbitrary finite elements.

- Elliptic equation:  $(-\Delta)^{lpha} u = f \ u|_{\partial\Omega} = 0$
- $u_{h,\alpha} = A_h^{-\alpha} \Pi_{0,h} f$ , where  $[A_h]_{i,j} = (\nabla \varphi_i | \nabla \varphi_j)_{L_2}$  and  $\Pi_{0,h} : L_2(\Omega) \to V_h L_2$ -orthogonal projection
- It was proved for  $L_2$  orthogonal finite element basis.
- Numerical experiments work in any basis.
- If  $\|u-u_h\|_0 \leq h^s \|f\|_0$ , then  $\|u_\alpha-u_{h,\alpha}\|_0 \leq h^{s\alpha} \|f\|_0$

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Matrix transformation method for finite elements

Space-fractional diffusion:

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$$\partial_t u(t,x) = -(-\Delta)^{\alpha} u(t,x)$$
  $u(0,x) = u_0(x)$ 

- Homogeneous Dirichlet or Neumann boundary conditions
- Method of lines: First finite element discretization in the spatial derivatives.
- Use some method to solve the ODE system.

$$\frac{E_h^{\alpha}u_{n+1} - E_h^{\alpha}u_n}{\delta} = A_h^{\alpha}u_{n+1}$$

 $u_0 = \Pi_{h,1} u_0(x)$  where  $[E_h]_{i,j} = (arphi_i | arphi_j)_{L_2}$ 

• Presumption: if  $\max_j \|u^j - u_h^j\| = O(k + h^s)$ , then  $\max_j \|u^j - u_{h,\alpha}^j\| = O(k + h^{\alpha s})$ 

#### Numerical results

#### Homogeneous Neumann

$$\partial_t u = -(1/13)^{0.7}(-\Delta)^{0.7}u$$
 on  $(0,1)x(0,\pi)^2$ 

$$u_0(x,y) = \cos(3x) \cdot \cos(2y)$$

- R4 elements
- spatial partition: N=15,30,60
- time partition: M=60
- L<sub>2</sub> norm of errors: 0.0263, 0.0133, 0.0077







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# How to solve the equations for nonomogeneous boundary coditions?

A possible way: for the

$$(-\Delta)^{\alpha} u = f$$
$$u|_{\partial \Omega} = g$$

problem we should find an extension  $\widehat{f}$  of f to  $\mathbb{R}^d$ , then solve the  $(-\Delta)^{\alpha}\widehat{u} = \widehat{f}$ , then if we restrict  $\widehat{u}$  to  $\omega$ , and  $\widehat{u}|_{\partial\Omega} = u|_{\partial\Omega}$ .

- Is there such an extension ?
- In one dimension the answer is yes.

Thank you for Your patience !

Image: A matrix

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