Dynamical systems, Sample Final Exam, May 35, 2022; 5.10am – 6.40

Show your work! Provide a clear, complete and detailed reasoning for each of the problems!

- 1. (a) Define the notions of a δ -chain (or δ -pseudo orbit) and of ε -shadowing. Using these, define what it means that a dynamical system satisfies the shadowing property! (6 points)
 - (b) Prove that the doubling map $T : \mathbb{S}^1 \to \mathbb{S}^1$, $Tx = 2x \pmod{1}$ satisfies the shadowing property. (14 points)
- 2. (a) What do we mean by a transition matrix (π_{ij}) , and an adjacency matrix (A_{ij}) , and when do we say that these are primitive (or irreducible and aperiodic)? Provide the definition of the associated topological Markov chain and of the associated Markov shift. (6 points)
 - (b) Prove that the associated Markov shift is mixing. (14 points)
- 3. Consider the rotation $T : \mathbb{S}^1 \to \mathbb{S}^1$, $Tx = x + 1/2 \pmod{1}$. Verify that the following two measures are invariant:

$$\mu_1 = \frac{1}{2} \left(\delta_{\frac{1}{3}} + \delta_{\frac{5}{6}} \right); \qquad \mu_2 = \frac{1}{4} \left(\delta_{\frac{1}{6}} + \delta_{\frac{1}{3}} + \delta_{\frac{2}{3}} + \delta_{\frac{5}{6}} \right).$$

Are μ_1 and/or μ_2 ergodic? Are they mixing (with respect to T)? (20 points)

4. Consider the linear maps $T : \mathbb{R}^2 \to \mathbb{R}^2$, T(x) = Ax for the matrices A below. In each case, describe the asymptotic behavior and sketch the phase portrait. In hyperbolic cases, determine the stable and unstable subspaces (W^s and W^u). (20 points)

(a)
$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$
 (b) $\begin{bmatrix} 1/3 & 1 \\ 0 & 3 \end{bmatrix}$ (c) $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ (d) $\begin{bmatrix} 2 & 2\sqrt{3} \\ -2\sqrt{3} & 2 \end{bmatrix}$.