## LECTURE 7: SEPARATION, FACES OF CONVEX SETS, EXTREMAL AND EXPOSED POINTS, THE KREIN-MILMAN THEOREM

We start with two theorems regarding separation.

**Theorem 1.** Let  $K, L \subset \mathbb{R}^n$  be convex sets with  $int(K) \neq \emptyset$  and  $int(K) \cap L = \emptyset$ . Then K and L can be separated by a hyperplane.

*Proof.* We have seen that if K is convex, then int(K) is convex (Exercise 3 on the first worksheet). But then by last theorem on the last lecture, the sets int(K) and L can be separated by a hyperplane. Since we learned that if  $int(K) \neq \emptyset$ , then  $K \subset cl(int(K))$ , and a hyperplane separating int(K) and L separates also cl(int(K)) and L, the assertion follows.

**Theorem 2.** If  $K, L \subset \mathbb{R}^n$  are disjoint, convex sets, K is compact and L is closed, then K and L can be strictly separated by a hyperplane.

Proof. We apply the idea of Theorem 4 in the first lecture. Let  $x \in K$ and  $y \in L$  be arbitrarily chosen points, and let r = ||y - x||. Let  $L_0$ be the set of the points of L whose distance from a point of K is at most r; in other words, let  $L_0 = L \cap (K + r\mathbf{B}^n)$ , where  $\mathbf{B}^n$  is the closed unit ball centered at o. Then the distance between any points of  $L \setminus L_0$ and K is greater than r, yielding that  $\operatorname{dist}(K, L) = \operatorname{dist}(K, L_0)$ , where  $\operatorname{dist}(A, B) = \inf\{||a - b|| : a \in A, b \in B\}$ . But both K and  $L_0$  are compact sets, and hence, there are points  $x \in K$  and  $y \in L$  for which  $\operatorname{dist}(x, y)$  is minimal. Let H be the hyperplane bisecting the segment [x, y]. Then H strictly separates K and L, as otherwise there are points  $x' \in K$  and  $y' \in L$  for which ||x' - y'|| < ||x - y||.

We have already seen (Corollary 4 in the first lecture) that for every boundary point of a convex set there is a hyperplane through the point such that the set is contained in one of the two closed half spaces bounded by the hyperplane. This is the motivation behind the following definitions.

**Definition 1.** Let  $K \subseteq \mathbb{R}^n$  be a convex set. If H is a closed half space satisfying  $K \subseteq H$  and whose boundary intersects the boundary of K, we say that H is a supporting half space of K, and the boundary of H is a supporting hyperplane of K.

**Definition 2.** Let  $K \subseteq \mathbb{R}^n$  be a closed, convex set and let H be a supporting hyperplane of K. Then the set  $H \cap K$  is called a proper face of K. The empty set is called a not proper face of K. The 0-dimensional faces (consisting of only one point) are called the exposed points of K, and their set is denoted by ex(K).

Our first observation implies the next remark in a natural way.

**Remark 1.** If  $K \subseteq \mathbb{R}^n$  is closed and convex, and  $p \in \mathbb{R}^n$  is a boundary point of K, then K has a proper face F such that  $p \in F$ .

**Problem 1.** Construct closed, convex sets which have no exposed points.

**Proposition 1.** If F is a proper face of the closed, convex set  $K \subseteq \mathbb{R}^n$ , then F is closed and convex.

*Proof.* Since every proper face F of K can be written as  $F = K \cap H$ , where H is a supporting hyperplane of K, and a hyperplane is closed and convex, the assertion follows from the fact that the intersection of closed, convex sets is closed and convex.

**Definition 3.** Let  $K \subseteq \mathbb{R}^n$  be closed and convex. If  $p \in bd K$ , and for every  $q, r \in K$ ,  $p \in [q, r]$  we have p = q or p = r, then we say that p is an extremal point of K. In other words, the extremal points of K are the points of K that are not relative interior points of a segment in K. The set of the extremal points of K is denoted by ext(K).

**Proposition 2.** If  $K \subseteq \mathbb{R}^n$  is closed and convex, then  $ex(K) \subseteq ext(K)$ .

Proof. Let p be an exposed point of K. Then there is a linear functional  $f: \mathbb{R}^n \to \mathbb{R}$  and a quantity  $\alpha \in \mathbb{R}$  such that  $K \subset f^{-1}([\alpha, \infty))$ , and  $K \cap f^{-1}(\alpha) = \{p\}$ . Assume that  $q, r \in K$  and  $p \in [q, r]$ . Then there is value  $t \in [0, 1]$  with p = tq + (1-t)r. By our conditions and the linearity of f, we have  $\alpha = f(p) = tf(q) + (1-t)f(r) \ge t\alpha + (1-t)\alpha = \alpha$ . But here, inequality occurs if and only if t = 1 and  $f(q) = \alpha$ , or t = 0 and  $f(r) = \alpha$ , or  $f(q) = f(r) = \alpha$ . But these yield p = q, p = r, and p = q = r, respectively, implying the statement.

**Example.** Let  $K \subseteq \mathbb{R}^2$  be the union of the unit square  $[0, 1]^2$  and the circular region defined by the inequality  $(x - 1/2)^2 + y^2 \leq 1/4$ .then o and the point (1, 0) are extremal points of K, but not exposed points of L. Thus, there are closed, convex sets K for which ex(K) and ext(K) do not coincide.

Our next theorem explores the connection between extremal points and linear functionals.

**Theorem 3.** Let  $K \subseteq \mathbb{R}^n$  be a closed, convex set, and let  $f : \mathbb{R}^n \to \mathbb{R}$ be a linear functional whose minimal or maximal value on K is  $\alpha$ . Let  $F = K \cap f^{-1}(\alpha)$ . Then  $p \in F$  is an extremal point of F if and only if it is an extremal point of K. In other words,  $ext(F) = ext(K) \cap f^{-1}(\alpha)$ .

Before proving Theorem 3, we observe that if  $p \in ex(K)$ , then there is a linear functional  $f : \mathbb{R}^n \to \mathbb{R}$  which attains its minimum on Konly at p. Thus, a consequence of this theorem is the containment  $ex(K) \subseteq ext(K)$  for every closed, convex set K.

*Proof.* Assume that  $p \in \text{ext}(K)$  and  $p \in F$ . Then, by the definition of extremal point, for any  $q, r \in K$ ,  $p \in [q, r]$  we have q = p or r = p. In particular, this holds also for any  $q, r \in F$ , implying that  $p \in \text{ext}(F)$ .

Now, let  $p \in \text{ext}(F)$ , and consider points  $q, r \in K$  with  $p \in [q, r]$ . If  $q \neq p$  and  $r \neq p$ , then for a suitable  $t \in (0, 1)$ , p = tq + (1 - t)r. But from this  $\alpha = f(p) = f(tq + (1 - t)r) = tf(q) + (1 - t)f(r)$ . As  $f(q), f(r) \geq \alpha$ , there is equality if and only if  $f(q) = f(r) = \alpha$ , azaz ha  $q, r \in F$ . But as  $p \in \text{ext}(F)$ , thiy yields q = p or r = p, which is a contradiction.  $\Box$ 

Our next theorem shows an important property of extremal points.

**Theorem 4** (Krein, Milman). Any compact, convex set  $K \subset \mathbb{R}^n$  is the convex hull of its extremal points.

*Proof.* We prove the statement by induction on the dimension. Assume that  $K \subset \mathbb{R}$  is a compact, convex set. Then K is a closed segment, whose extremal points are its endpoints, and the segment is the convex hull of its endpoints. Thus, the assertion holds for n = 1.

Assume that the statement is true for any at most (n-1)-dimensional compact, convex set, and let K be K an n-dimensional compact, convex set. Let  $p \in K$  be arbitrary, and let L bi an arbitrary line through p. According to our conditions,  $L \cap K$  is a closed finite segment. Let the endpoints of this segment be q and r, where these points may not be distinct from each other or p. Then, by Remark 1, there are faces  $F_q$  and  $F_r$  of K such that  $q \in F_q$  and  $r \in F_r$ . But as  $F_q$  and  $F_r$  are convex subsets of the boundary of K, they have no interior points, and thus, by Lemma 2 of the fourth lecture, they are at most (n-1)-dimensional compact, convex sets. By the induction hypothesis, we have  $q \in \operatorname{conv} \operatorname{ext}(F_q)$  és  $r \in \operatorname{conv} \operatorname{ext}(F_r)$ . But by the definition of face, there are linear functionals  $f_q : \mathbb{R}^n \to \mathbb{R}$  and  $f_r : \mathbb{R}^n \to \mathbb{R}$ attaining their minima exactly at  $F_q$  and  $F_r$ , respectively, and thus, by Theorem 3, the extremal points of  $F_q$  and  $F_r$  are extremal points of K. But then  $p \in [q, r] \subseteq \operatorname{conv}(\operatorname{ext}(F_q) \cup \operatorname{ext}(F_r)) \subseteq \operatorname{conv}(\operatorname{ext}(K))$ .  We have seen that the extremal points of a set are not necessarily exposed points. On the other hand, it is true that they are accumulation points of sequences of exposed points.

**Theorem 5** (Straszevicz). For any compact, convex set  $K \subset \mathbb{R}^n$  we have K = cl(conv(ex(K))); or in other words, K is equal to the closure of convex hull of its exposed points.

*Proof.* Let  $x \in \text{ext}(K)$  and  $\varepsilon > 0$  be arbitrary. Let us consider the compact, convex set  $K_{\varepsilon} = \text{conv}(K \setminus \text{int } B_{\varepsilon}(x)) \subseteq K$ , where  $B_{\varepsilon}(x)$  denotes the closed ball of radius  $\varepsilon$  and center x. If  $x \in K_{\varepsilon}$ , then by the Carathéodory theorem it is the convex combination of at most n + 1 points of  $(K \setminus \text{int } B_{\varepsilon}(x))$ ; that is, it is a relative interior point of a segment in K. But this contradicts the assumption that  $x \in \text{ext}(K)$ , and thus,  $x \notin K_{\varepsilon}$ .

Note that  $K_{\varepsilon}$  is a compact, convex set, and thus, it can be strictly separated from p. In other words, there is a hyperplane H such that one of the closed half spaces bounded by it intersects K in a subset of  $B_{\varepsilon}(x)$ , and this half space contains x in its interior. Let  $H^+$  denote this closed half space. Let L be the half line starting at x, perpendicular to H and intersecting H. For any  $y \in L$  let z(y) be a farthest point of K from y. Then  $z(y) \in ex(K)$  for any  $y \in L$  (see Problem sheet 5, Exercise 4). On the other hand, if y is sufficiently far from x, then  $z(y) \in B_{\varepsilon}(x)$ . Thus  $x \in cl(ex(K))$ , from which  $ext(K) \subseteq cl(ex(K))$ .

By the containment relation  $\operatorname{conv}(\operatorname{cl}(X)) \subseteq \operatorname{cl}(\operatorname{conv}(X))$ , satisfied for any set  $X \subseteq \mathbb{R}^n$ , and by the Krein-Milman Theorem, we have

 $K \subseteq \operatorname{conv}(\operatorname{ext}(K)) \subseteq \operatorname{conv}(\operatorname{cl}(\operatorname{ex}(K))) \subseteq \operatorname{cl}(\operatorname{conv}(\operatorname{ex}(K))) \subseteq K,$ that is,  $K = \operatorname{cl}(\operatorname{conv}(\operatorname{ex}(K))).$ 

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