

LECTURE 8: CONVEX POLYTOPES

Our next topic is the theory of convex polytopes. Our main concept is as follows.

Definition 1. *The convex hull of finitely many points in \mathbb{R}^n is called a convex polytope, or shortly, polytope. If $P \subset \mathbb{R}^n$ is a convex polytope, then the set $\{x_1, x_2, \dots, x_k\} \subset \mathbb{R}^n$ is a minimal representation of P , if*

- (i) $P = \text{conv}\{x_1, x_2, \dots, x_k\}$, and
- (ii) for any index i , we have $x_i \notin \text{conv}\{x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_k\}$.

Let us observe that every convex polytope has a minimal representation, which can be obtained by removing redundant points one by one from any representation. It is worth noting that the exposed points (that is, 0-dimensional faces) of a convex polytope are usually called *vertices*, and the $(n - 1)$ -dimensional faces of a convex polytope are called *facets*.

Theorem 1. *Let $M = \{x_1, \dots, x_k\} \subset \mathbb{R}^n$ be a minimal representation of the convex polytope P . Then the following are equivalent:*

- (i) $x \in M$,
- (ii) $x \in \text{ex}(P)$,
- (iii) $x \in \text{ext}(P)$.

Proof. First, we show that (i) implies (ii). Assume that $x \in M$. Then $x \notin \text{conv}(M \setminus \{x\})$. Since $\text{conv}(M \setminus \{x\})$ is compact and convex, there is a hyperplane H that strictly separates it from x . Let H_0 be the hyperplane parallel to H and containing x . Then $H_0 \cap M = \{x\}$ and H_0 is a supporting hyperplane of $P = \text{conv}(M)$. By Proposition 1 of the second lecture, then $H_0 \cap P = H_0 \cap \text{conv}(M) = \text{conv}(H_0 \cap M) = \{x\}$, and hence, x is a vertex of P .

By Proposition 2 of the fifth lecture, for any closed, convex set K we have $\text{ex}(K) \subseteq \text{ext}(K)$. As M is compact, so is its convex hull; that is, (ii) implies (iii). We will show that (iii) implies (i). Let $x \in \text{ext}(P)$. Now, if $x \in \text{conv}(M \setminus \{x\})$ was true, then x could be written as a convex combination of points from $M \setminus \{x\}$. Choosing a minimal number of such points one can show that then x could be written as a relative interior point of a segment in P , which would contradict the condition that $x \in \text{ext}(P)$. \square

Corollary 1. *Every convex polytope has a unique minimal representation.*

Remark 1. By Proposition 1 of the second lecture, if H is a supporting hyperplane of the convex set $\text{conv}(X)$, then $H \cap \text{conv}(X) = \text{conv}(H \cap X)$. From this it follows that every face of a convex polytope is a convex polytope, and also that every convex polytope has only finitely many faces.

The next two statements hold for the faces of every compact, convex sets.

Proposition 1. If $K \subset \mathbb{R}^n$ is a nonempty, compact, convex set, and F_1, \dots, F_m are faces of K , then $F = \bigcap_{i=1}^m F_i$ is a face of K .

Proof. If $F = \emptyset$, then F is a face of K , and thus, we may assume that $F \neq \emptyset$, which implies that for every i , F_i is a proper face of K . Without loss of generality, we may assume that $o \in F$. Since F_i is a proper face of K , there is a linear functional $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$ satisfying $f_i(x) \geq 0$ for all $x \in K$, and for which $f_i(x) = 0$ for some $x \in K$ if and only if $x \in F_i$. Now, let $f = \sum_{i=1}^m f_i$. This function f is a linear functional, and if $x \in K$, then $f(x) \geq 0$. Assume that $x \in K$ and $f(x) = 0$. From this, $\sum_{i=1}^m f_i(x) = 0$, but since $f_i(x) \geq 0$ for any value of i , this is satisfied if and only if $f_i(x) = 0$ for all values of i , or in other words, if $x \in F$. Thus, F is a face of K . \square

Proposition 2. Let $S_2 \subseteq S_1 \subset \mathbb{R}^n$ be compact, convex sets. If F is a face of S_1 , then $F \cap S_2$ is a face of S_2 .

Proof. If $F \cap S_2 = \emptyset$, then it is clearly a face of S_2 . Assume that $F \cap S_2 \neq \emptyset$, which implies that F is a proper face of S_1 . Let H be a supporting hyperplane of S_1 satisfying $H \cap S_1 = F$. Then H also supports S_2 , and $H \cap S_2 = (H \cap S_1) \cap S_2 = F \cap S_2$, implying that $F \cap S_2$ is a face of S_2 . \square

Our next proposition, which, in some sense, is the converse of the previous one, holds only for convex polytopes.

Proposition 3. Let F_1 be a proper face of a convex polytope P , and let F_2 be a face of F_1 . Then F_2 is a face of P .

Proof. If $F_2 = \emptyset$, then the statement holds, and hence, we may assume that F_2 is a proper face of F_1 . According to our conditions, P has a supporting hyperplane H in \mathbb{R}^n satisfying $P \cap H = F_1$, and if F_2 is a proper face of F_1 , then there is a ‘supporting hyperplane’ G of F_2 in H satisfying $G \cap F_1 = F_2$. Observe that $\dim G = n - 2$. As P is a convex polytope, only finitely many vertices of P are not elements of H , and thus, H can be rotated around G with a sufficiently small angle in a suitable direction such that the hyperplane H' obtained by

this rotation is a supporting hyperplane of P , and, from amongst the vertices of P , it contains only those in F_2 . But from this, it follows that $H' \cap P = F_2$, yielding that F_2 is a face of P . \square

Problem 1. *Construct a compact, convex set $K \subseteq \mathbb{R}^n$ with the property that it has a proper face F_1 , and F_1 has a proper face F_2 such that F_2 is not a face of K .*

We have seen that every compact, convex set can be obtained as the intersection of closed half spaces. Now we show that a convex polytope is the intersection of finitely many closed half spaces (namely those defined by its facets).

Definition 2. *The intersection of finitely many closed half spaces is called a polyhedral set.*

Theorem 2. *Every convex polytope is a bounded polyhedral set.*

Proof. Let $P \subset \mathbb{R}^n$ be a convex polytope. As P is compact, it is sufficient to prove that it is a polyhedral set. Without loss of generality, assume that $\dim P = n$, as every hyperplane is obtained as the intersection of the two closed half spaces it generates, and every affine subspace is obtained as the intersection of finitely many hyperplanes.

Let $M = \{x_1, \dots, x_k\}$ be a minimal representation of P . Let the facets of P be F_1, \dots, F_m , and denote by H_i and H_i^+ the supporting hyperplane and the closed supporting half space defined by F_i , respectively. Then for any index i , we have $P \cap H_i = F_i$ and $P \subset H_i^+$. We show that $P = \bigcap_{i=1}^m H_i^+$.

Clearly, $P \subseteq \bigcap_{i=1}^m H_i^+$, and thus, by contradiction, we suppose that there is a point $x \in (\bigcap_{i=1}^m H_i^+) \setminus P$. Now, let $D = \bigcup \text{aff}(\{x\} \cup C)$, where C runs over the family of the subsets of M of cardinality at most $(n-1)$. Then D is the union of finitely many affine subspaces of dimension at most $(n-1)$, and thus, we can choose a point $y \in \text{int}(P)$ with $y \notin D$. But then, by $x \notin P$, the segment $[x, y]$ intersects the boundary of P , that is, there is a point $z \in (x, y)$ with $z \in \text{bd}(P)$. We will show that z lies on a facet of P , but it does not lie on any lower dimensional face of P .

Assume that $z \in F$ for some j -dimensional face of P , where $0 \leq j \leq n-2$. Then, by Carathéodory's theorem, z is contained in the convex hull of at most $(n-1)$ points of M , implying $\text{aff}\{x, z\} \in D$, which contradicts the assumption that $y \notin D$. By Corollary 4 of the first lecture, any boundary point of a compact, convex set is a point of a supporting hyperplane of the set, and thus, a point of a proper face of the set. Thus, by exclusion, z is a point of a facet F_i of P . But from

this, by $y \in \text{int } P \subset \text{int } H_i^+$, we obtain $x \notin H_i$, which contradicts our choice of y . This yields that $P = \bigcap_{i=1}^m H_i^+$. \square

Corollary 2. *The boundary of every n -dimensional convex polytope $P \subset \mathbb{R}^n$ is the union of the facets of P .*