# Convex Geometry tutorial for students with mathematics major

## Problem sheet 4 - Hyperplanes, Minkowski sum, separation -Solutions

**Exercise 1.** Prove that if A and B are two disjoint, convex sets in  $\mathbb{R}^n$ , then there are disjoint convex sets A', B' in  $\mathbb{R}^n$  satisfying  $A \subset A'$ ,  $B \subset B'$ , and  $A' \cup B' = \mathbb{R}^n$ .

## Solution

We prove the statement by induction on n. Let n = 1. If, e.g.  $L = \emptyset$ , then  $K^* = \mathbb{R}^1$  and  $L^* = \emptyset$ satisfy the required conditions. If K and L are not empty, then by the Separation Theorem there is a point p such that hogy one of the two closed half lines starting at p contains K, and the other one contains L. Let these two half lines be  $E_1$  and  $E_2$  such that  $K \subseteq E_1$  and  $L \subseteq E_2$ . Since Kand L are disjoint, we can assume that e.g.  $p \notin L$ . Then  $K^* = E_1$  and  $L^* = E_2 \setminus \{p\}$  satisfy the required conditions.

Now, assume that the statement holds in  $\mathbb{R}^k$  for any k < n. If e.g.  $L = \emptyset$ , then  $K^* = \mathbb{R}^n$  és  $L^* = \emptyset$  satisfy the conditions. In the opposite case, as K and L are disjoint, convex sets, there is a hyperplane H that (not necessarily strictly) separates K and L. Let the two open half spaces bounded by H be denoted by  $H_+$  and  $H_-$ , where  $K \subseteq H \cup H_+$  and  $L \subseteq H \cup H_-$ . The sets  $H \cap K$  and  $H \cap L$  are convex, being the intersections of convex sets, and they are disjoint. Since H is an (n-1)-dimensional Euclidean space, we may apply the induction hypothesis, and obtain that there are disjoint, convex sets  $K_H^*$  and  $L_H^*$ , for which  $H \cap K \subseteq K_H^*$ ,  $H \cap L \subseteq L_H^*$ , and  $H = K_H^* \cup L_H^*$ . Let  $K^* = H_+ \cup K_H^*$  and  $L^* = H_- \cup L_H^*$ . These sets are disjoint, and their union is  $\mathbb{R}^n$ . We show that they are convex.

CLearly, it is sufficient to show that  $K^*$  is convex. Let  $p, q \in K^*$ . If  $p, q \in K^*_H$ , then by the convexity of  $K^*_H$  we have  $[p,q] \subseteq K^*_H \subset K^*$ . Let, e.g.  $p \in H_+$ . Then for any point  $r \in [p,q], r \neq q$  we have  $r \in H_1 \subset K^*$ , therefore  $[p,q] \subseteq K^*$ , implying that  $K^*$  is convex. Thus,  $K^*$  and  $L^*$  satisfy the conditions of the exercise.

**Exercise 2.** Describe all decompositions of the 3-dimensional Euclidean space into the union of two disjoint, convex sets. What is the situation in  $\mathbb{R}^n$ ?

#### Solution

Let us call a set X in  $\mathbb{R}^n$  a suitable set, if  $X = \emptyset$ ,  $X = \mathbb{R}^n$ , or for some  $1 \le k \le n$  there are sets  $H^1_+, H^2_+, \ldots, H^k_+, H^k$  such that

- (i)  $H^1_+$  is an open half space in  $\mathbb{R}^n$ ,  $H^2_+$  is an open half space in the boundary of  $H^1_+$ , and in general, for every  $2 \le m \le k$ ,  $H^m_+$  is an open half space in the relative boundary of  $H^{m-1}_+$ ,
- (ii)  $H^k$  is the relative boundary of  $H^k_+$ ,
- (iii)  $X = \bigcup_{i=1}^{k} H^{i}_{+}$  (first type suitable set), or  $X = H_{k} \cup \bigcup_{i=1}^{k} H^{i}_{+}$  (second type suitable set).

by the argument used in the previous exercise, every suitable set is convex, and the complement of a first type suitable set is a second type suitable set, and vice versa. Therefore any decomposition of  $\mathbb{R}^n$  into the union of two suitable sets satisfies the conditions. We show that if K and L are convex sets whose disjoint union is  $\mathbb{R}^n$ , then K and L are suitable sets.

We prove the statement by induction on n. We may assume that K and L are not empty. Applying the idea of the solution of Exercise 1, we have that in this case one of K and L is a closed half line and the other one is an open half line, which are suitable sets. Assume that the statement is true for the decompositions of  $\mathbb{R}^{n-1}$ , and let K, L be disjoint, convex sets satisfying  $K \cup L = \mathbb{R}^n$ . The sets  $\emptyset$ ,  $\mathbb{R}^n$  satisfy the conditions. If K and L are not this pair, then by the Separation Theorem there is a hyperplane  $H^1$  separating K and L, and thus, suitably labelling the open half planes  $H^1_+, H^1_-$  bounded by  $H^1$ , we have  $K \subseteq H^1 \cup H^1_+$  and  $L \subseteq H^1 \cup H^1_-$ , from which  $H^1_+ \subseteq K$  and  $H^1_- \subseteq L$ . Let  $K^1 = K \cap H^1$  and  $L^1 = L \cap H^1$ . Then  $K = K^1 \cup H^1_+$  and  $L = L^1 \cup H^1_-$ . On the other hand,  $K^1$  and  $L^1$  are disjoint, convex sets, and  $K^1 \cup L^1 = H^1$ , which, by the induction hypothesis, implies that  $K^1$  and  $L^1$  are suitable sets in  $H^1$ . But then K and L are suitable sets in  $\mathbb{R}^n$ .

**Exercise 3.** (a) Let T be a regular triangle. What is T - T? What is T + T?

(b) For any compact set  $T \subset \mathbb{R}^n$  and positive integer k let  $T_k = \underbrace{\overline{T + T + \ldots + T}}_{k}$ . Prove that if T is convex and  $k \in \mathbb{Z}^+$ , then

$$T_k = T.$$

If T is not necessarily convex, what is the relationship between T,  $T_k$  and  $\operatorname{conv}(T)$ ? (c)\* Prove that if  $T \subset \mathbb{R}^n$  is compact and convex  $\operatorname{and} k \in \mathbb{Z}^+$ , then

$$V(T_k) \le V(T_{k+1}),$$

where  $V(\cdot)$  denotes *n*-dimensional volume (Lebesgue measure). What happens if T is not necessarily convex?

## Solution

a) Observe that for any  $A, B \subset \mathbb{R}^n$  and  $x, y \in \mathbb{R}^n$  we have (x + A) + (y + B) = (x + y) + (A + B), that is, the vector sum of translates of two given sets is a translate of the vector sum of the sets. Thus, up to translation, T - T is independent of the choice of the origin, and we may assume that one vertex of T is o, implying that -T is the reflection of T about that vertex. On the other hand, for any sets  $A, B \subset \mathbb{R}^n, A+B = \bigcup_{a \in A} (\{a\}+B)$ , that is, T-T can be obtained by sliding -T along all points of T, and taking the union of all these translates of -T. In this waay one can see that T - T is a regular hexagon centered at o, with edge length equal to the edge length of T and -T, and containing one of the edges of both these triangles in its boundary. We obtain similarly that if o is a vertex of T, then T + T = 2T, that is, T + T coincides with the image of T under the central similarity of center o and ratio 2. If it is not true, then T can be written in the form  $T = x + T_0$ , where a vertex of  $T_0$  is o. But then  $T + T = (x + T_0) + (x + T_0) = 2x + (T_0 + T_0) = 2x + 2T_0 = 2T$ , and the previous statement holds also in the general case, that is, T + T coincides with the image of T under the image of T under the central similarity of center o and ratio 2. In other words, T + T = 2T.



b) By the definition of Minkowski sum,

$$2T=\{x+x:x\in T\}\subseteq \{x+y:x,y\in T\}=T+T$$

for any nonempty set, from which  $T \subseteq T_2$  follows. One can see similarly that  $T \subseteq T_k$  for any nonempty set T and integer  $k \in \mathbb{Z}^+$ . On the other hand, since the elements of  $T_k$  are convex combinations of points of T, we also have  $T_k \subseteq \text{conv}(T)$ . If T is convex, then T = conv(T), implying that then  $T_k = T$  for any positive integer k.

One can ask whether the relation  $T_k \subseteq T_m$  also holds for any positive integers  $k \leq m$ , even if T is not necessarily convex. This is not true in general, as shown by the set  $T = [o, e_1] \cup [o, e_2] \subset \mathbb{R}^2$ , where  $e_1, e_2$  is the usual basis of the plane. Then, e.g.  $T_2 \not\subseteq T_3$ , as shown in the figure.



c) One can present the above example in a more general way. Let  $K_1$  and  $K_2$  be *n*-dimensional unit cubes in two orthogonal *n*-dimensional linear subspaces of  $\mathbb{R}^{2n}$ , and let  $S = K_1 \cup K_2$ . Let

$$S[k] = \overbrace{S + \ldots + S}^{K}. \text{ Then}$$

$$S[2] = S + S = (K_1 + K_1) \cup (K_1 + K_2) \cup (K_2 + K_1) \cup (K_2 + K_2) = (2K_1) \cup (K_1 + K_2) \cup (2K_2),$$

$$S[2] = S + S = (K_1 + K_1) \cup (K_1 + K_2) \cup (K_2 + K_1) \cup (K_2 + K_2) = (2K_1) \cup (K_1 + K_2) \cup (2K_2),$$

implying  $\operatorname{vol}(S[2]) = 1$ . Similarly,  $S[3] = \bigcup_{i=0}^{3} (iK_1 + (k-i)K_2)$ . Since  $(2K_1 + K_2) \cap (K_1 + 2K_2) = K_1 + K_2$ , we have  $\operatorname{vol}(S[3]) = 2 \cdot 2^n - 1$ . But this implies  $\operatorname{vol}(S[3]/3) = \frac{2^{n+1}-1}{3^{2n}} < \operatorname{vol}(S[2]) = \frac{1}{2^{2n}}$ , if *n* is sufficiently large.

**Exercise 4.** Let the sum of the planar vectors  $a_1, a_2, \ldots, a_k$  be o. Assume that among these vectors there are no two with the same direction. Prove that up to translation there is a unique convex polygon whose sides, oriented according to a fixed orientation of the plane, are exactly these vectors.

## Solution

Draw these vectors in such a way that their starting points are o, and label them such that  $a_1, a_2, \ldots, a_k$  are exactly in this order around o in counterclockwise order. Let P be an arbitrary convex polygon whose side vectors (oriented in counterclockwise order) are  $a_1, a_2, \ldots, a_k$  in counterclockwise order. Let us walk around on the boundary of P in counterclockwise order. Then at every vertex we turn to the left with an angle between 0 and  $\pi$  (this angle is called *turning angle*). In case of a convex polygon, the sum of these turning angles is  $2\pi$ , and thus, the side vectors of P are  $a_1, a_2, \ldots, a_k$  if and only if they appear in this order in the boundary of P, that is, up to translation, P is unique.

Now, let Q be the polygonal curve obtained by connecting the points  $o, a_1, a_1 + a_2, \ldots, a_1 + \ldots + a_k$  in this order. Since  $\sum_{i=1}^k a_i = o, Q$  is a closed polygonal curve. Let  $L_i$  be the line through the points  $a_1 + \ldots + a_{i-1}$  and  $a_1 + \ldots + a_i$ .

We show that  $L_i$  is a sideline of Q, that is, one of the two closed half planes bounded by  $L_i$  contains Q. Since the labelling of the points is cyclic, it is sufficient to show it for the line  $L_1$  containing the segment  $[0, a_1]$ . Using a suitable coordinate system we may assume that  $a_1 = (0, x_1)$  for some suitable  $x_1 > 0$ . Let  $a_i = (x_i, y_i), x_i, y_i \in \mathbb{R}$  for all values of i. By the choice of the indices, there is some index 1 < m < k such that  $y_1, \ldots, y_m \ge 0$ , and  $y_{m+1}, \ldots, y_k < 0$ . But the y-coordinates of the vertices of Q are  $0, y_1 = 0, y_1 + y_2, y_1 + y_2 + y_3, \ldots, y_1 + \ldots + y_k = 0$  in this order, and thus, this sequence is increasing up to  $y_1 + \ldots + y_m$ , and decreasing after that, which implies that all vertices of Q, and also Q, are contained in the closed half space  $\{(x, y) \in \mathbb{R}^2 : y \ge 0\}$ .



**Exercise 5.** Let K and L be convex polygons, whose edge vectors, according to a fixed orientation of the plane, are  $a_1, \ldots, a_k$  and  $b_1, \ldots, b_m$ , respectively. Prove that if, among the vectors, there are no two in the same direction, then K + L is a convex polygon whose edge vectors are exactly  $a_1, \ldots, a_k, b_1, \ldots, b_m$ . How can we modify the statement if there are vectors with the same direction?

## Solution

We use the notation of the previous exercise, and assume that the vectors  $a_i$  and  $b_j$  are labelled in such a way that starting with the direction of the positive half of the x-axis, their order according to positive (counterclockwise) orientation is  $a_1, a_2, \ldots, a_k$ , and  $b_1, b_2, \ldots, b_m$ , respectively. In addition, let  $c_1, c_2, \ldots, c_{k+m}$  be the vector system, ordered according to positive orientation starting with the positive half of the x-axis, satisfying  $\{c_1, \ldots, c_{k+m}\} = \{a_1, \ldots, a_k\} \cup \{b_1, \ldots, b_m\}$ . Let M be the convex polygon whose vertices are  $o, c_1, c_1 + c_2, \ldots, c_1 + \ldots + c_{k+m} = o$  in this order. We show that M = K + L.

Observe that every vertex of M can be written in the form  $(a_1 + \ldots + a_i) + (b_1 + \ldots + b_j)$  for some suitable indices i and j, and hence, every vertex of M is the sum of a vertex of K and a vertex of L, which implies  $M \subseteq K + L$ . We show that the line E through  $[o, c_1]$  is a supporting line of K + L. To do this, we may assume that  $c_1 = a_1$ , and E coincides with the x-axis. Then, by the consideration in the previous problem, it follows that the y-coordinates of every vertex of K and L is nonnegative. We can say the same for all the convex combinations of these vertices, which implies that E is a supporting line of K + L. Similarly, one can see that every sideline (and similarly every supporting line) of M is a supporting line of K + L. Since a compact, convex set can be written as the intersection of its supporting half planes, from this M = K + L follows.

If among the vectors there are some in the same direction, then the statement also holds, which can be shown, e.g. by a limit argument.

**Definition.** If  $K \subset \mathbb{R}^n$  is compact, convex, and  $\operatorname{int} K \neq \emptyset$ , then we say that K is a convex body. The perimeter of a plane convex body K is the supremum of the perimeters of the convex polygons contained in K, if it exists. Its notation:  $\operatorname{perim}(K)$ .

**Remark.** It can be shown that every plane convex body has a perimeter, and if  $K \subseteq L$  are plane convex bodies, then  $\operatorname{perim}(K) \leq \operatorname{perim}(L)$ .

**Exercise 6.** Let K and L be plane convex bodies. Prove that then  $\operatorname{perim}(K + L) = \operatorname{perim}(K) + \operatorname{perim}(L)$ .

**Solution**. Let  $\varepsilon > 0$  be arbitrary. By the definition of perimeter, there are convex polygons  $P \subseteq K, Q \subseteq L$  satisfying  $0 \leq \operatorname{perim}(K) - \operatorname{perim}(P) < \frac{\varepsilon}{2}$  and  $0 \leq \operatorname{perim}(L) - \operatorname{perim}(Q) < \frac{\varepsilon}{2}$ . Then,

by the properties of vector sum, we have  $P + Q \subseteq K + L$ , implying  $\operatorname{perim}(P + Q) \subseteq \operatorname{perim}(K + L)$ . But, by the previous exercise,  $\operatorname{perim}(P + Q) = \operatorname{perim}(P) + \operatorname{perim}(Q)$ , and thus,  $\operatorname{perim}(K + L) > \operatorname{perim}(K) + \operatorname{perim}(L) - \varepsilon$  for any  $\varepsilon > 0$ , which implies  $\operatorname{perim}(K + L) \ge \operatorname{perim}(K) + \operatorname{perim}(L)$ .

On the other hand, let  $X \subset K+L$  be a convex polygon satisfying  $\operatorname{perim}(X) > \operatorname{perim}(K+L) - \varepsilon$ . Let  $X = \operatorname{conv}\{x_i + y_i : x_i \in K, y_i \in L, i = 1, 2, \dots, m\}$ . Let  $P = \operatorname{conv}\{x_i : i = 1, \dots, m\} \subseteq K$  and  $Q = \operatorname{conv}\{y_i : i = 1, 2, \dots, m\} \subseteq L$ . Then  $X \subseteq P + Q \subseteq K + L$ . By the definition of perimeter,  $X \subseteq P + Q$  implies  $\operatorname{perim}(X) \leq \operatorname{perim}(P + Q) = \operatorname{perim}(P) + \operatorname{perim}(Q) \leq \operatorname{perim}(K) + \operatorname{perim}(L)$ , which yields  $\operatorname{perim}(K) + \operatorname{perim}(L) \geq \operatorname{perim}(K+L) - \varepsilon$  for any  $\varepsilon > 0$ . Hence,  $\operatorname{perim}(K) + \operatorname{perim}(L) \geq \operatorname{perim}(K+L)$ . Comparing it to the inequality at the end of the previous paragraph, we obtain the desired equality.